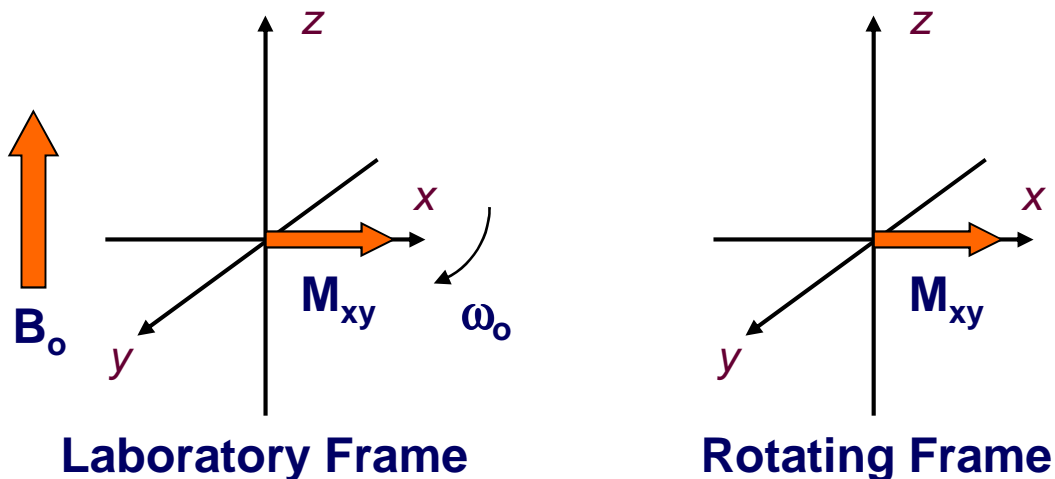


Laboratory and Rotating frames

- The coordinate system that we used for the previous example (**laboratory frame**) is really pathetic. The whole system is spinning at ω_0 , which makes any kind of analysis impossible.
- Again, an out-of-date example. It would be like trying to read the label of a record spinning in a turn-table...
- The solution is to take a coordinate system that moves at ω_0 . This is like jumping on top of the long play to read the label. What we effectively do is remove the effect of \mathbf{B}_0 . If we take magnetization on the $\langle xy \rangle$ plane:



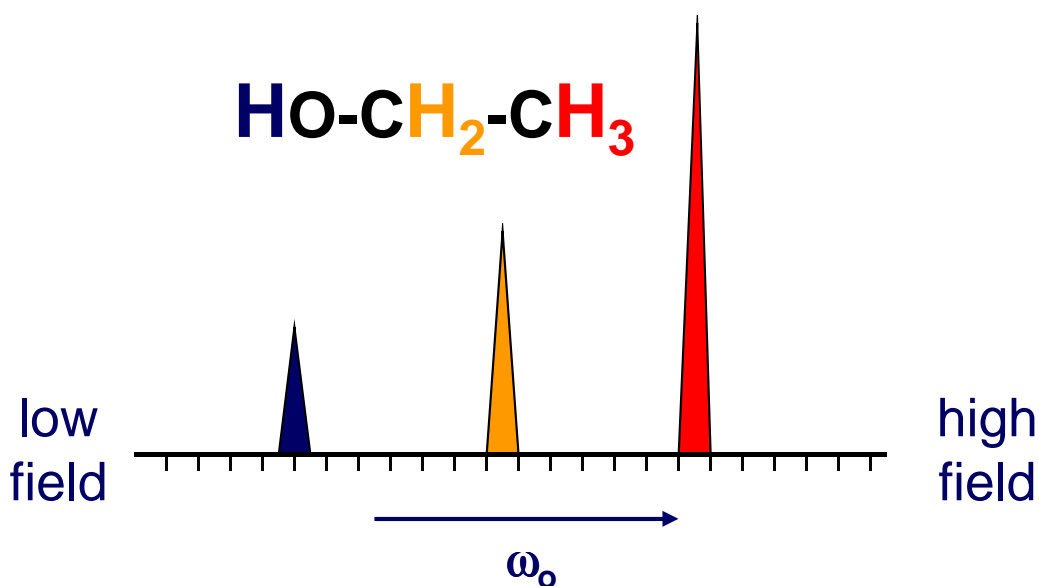
- In this coordinate system, \mathbf{M}_{xy} does not move if we are at the resonant condition (the ω of \mathbf{B}_1 is exactly the frequency of the nuclei, ω_0). If we are slightly off-resonance, the movement of the vectors is still slow with respect to ω_0 .

Chemical shifts

- If each type of nucleus has its characteristic ω_0 at a certain magnetic field, why is NMR useful?
- Depending on the **chemical environment** we have variations on the magnetic field that the nuclei feels, even for the same type of nuclei. It affects the local magnetic field.

$$B_{\text{eff}} = B_0 - B_{\text{loc}} \quad \text{---} \quad B_{\text{eff}} = B_0(1 - \sigma)$$

- σ is the **magnetic shielding** of the nucleus. Factors that affect it include neighboring atoms and groups, etc., etc. The polarization of the bonds to the observed nuclei are important as well.
- As a crude example, ethanol looks like this:



The NMR scale (δ , ppm)

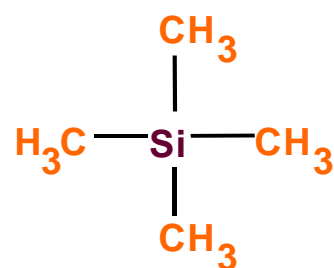
- We can use the frequency scale as it is. The problem is that since B_{loc} is a lot smaller than B_0 , the range is very small (hundreds of Hz) and the absolute value is very big (MHz).
- We use a relative scale, and refer all signals in the spectrum to the signal of a particular compound.

$$\delta = \frac{\omega - \omega_{\text{ref}}}{\omega_{\text{ref}}}$$

ppm (parts per million)

- The good thing is that since it is a relative scale, the δ in a 100 MHz magnet (2.35 T) is the same as that obtained for the same sample in a 600 MHz magnet (14.1 T).

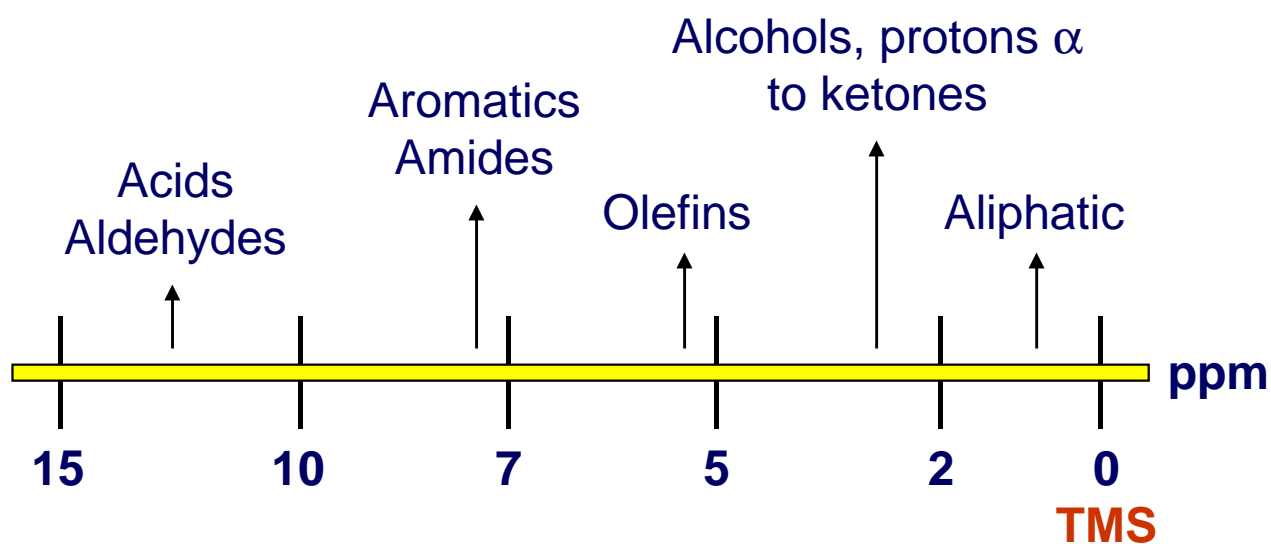
- **Tetramethyl silane (TMS)** is used as reference because it is soluble in most organic solvents, inert, volatile, and has 12 equivalent ^1H s and 4 equivalent ^{13}C s:



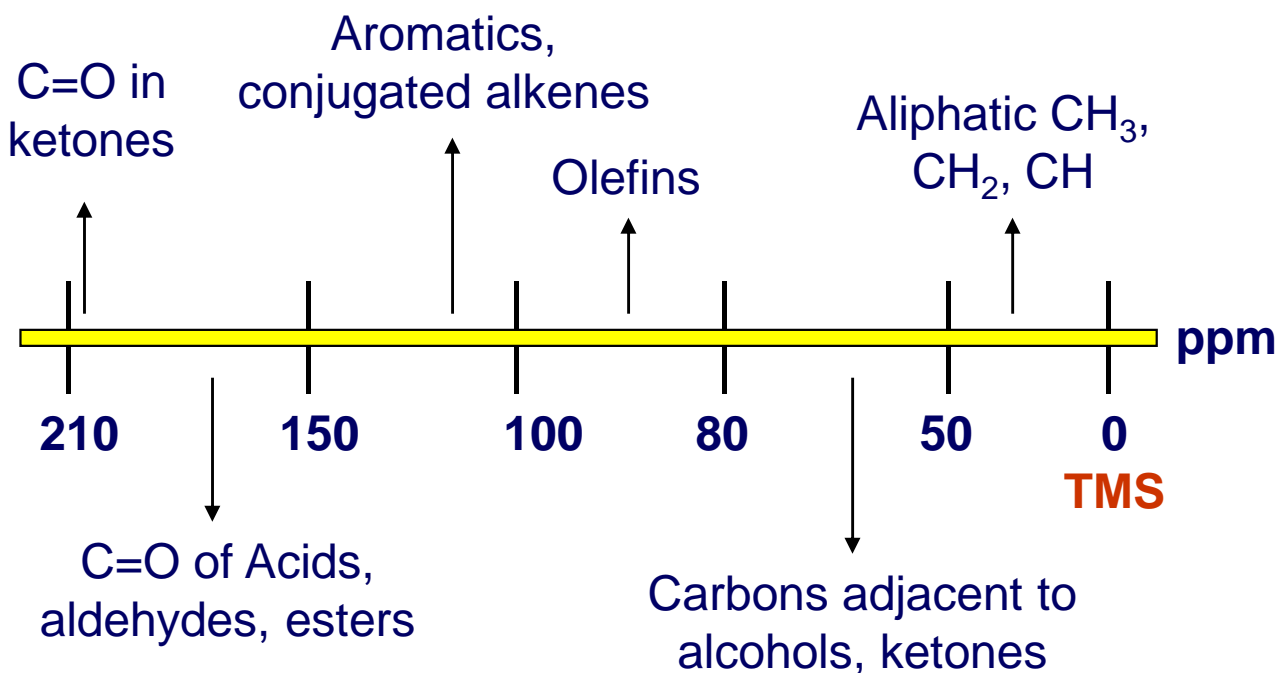
- Other references can be used, such as the residual solvent peak, dioxane for ^{13}C , etc. What reference we use is not critical, because the instrument (software/hardware) is calibrated internally. Don't use them if you don't need to...

Scales for different nuclei

- For protons, ~ 15 ppm:

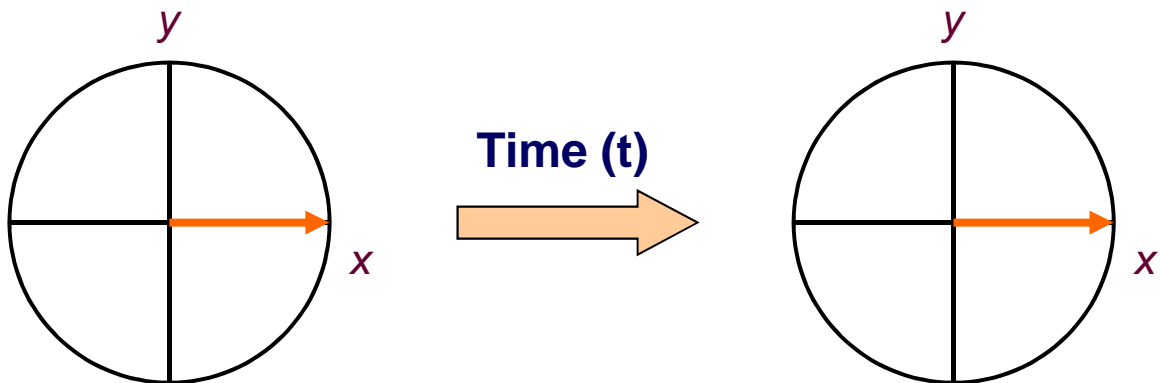


- For carbon, ~ 220 ppm:

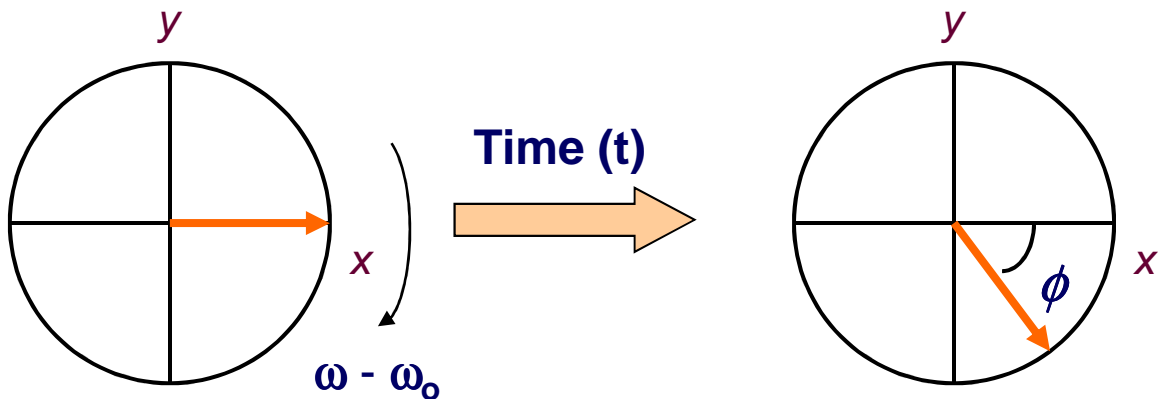


Chemical shift in the rotating frame

- We will consider only magnetization in the $\langle xy \rangle$ plane. We start with a signal with an ω_0 equal to the ω of \mathbf{B}_1 . After some time passes, nothing changes...



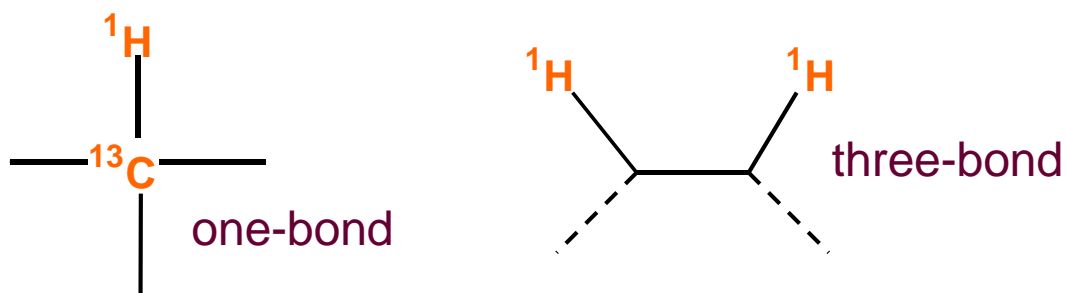
- Now, if we are slightly off-resonance ($\omega - \omega_0 \neq 0$), the \mathbf{M}_{xy} vector will evolve with time. The angle will be proportional to the evolution time and $\omega - \omega_0$ (that's why we use radians...)



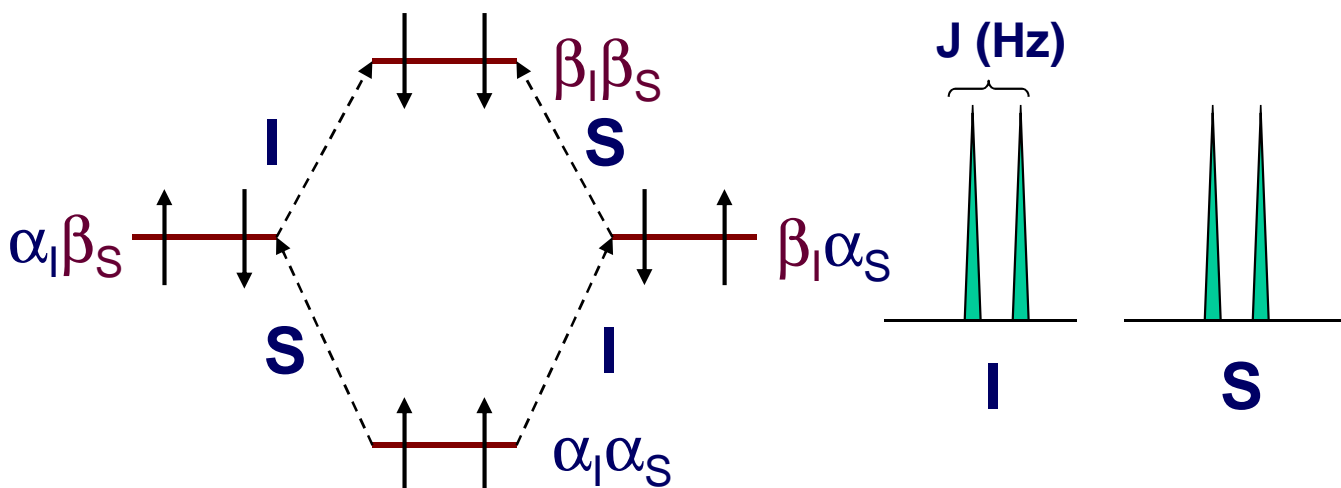
$$\phi = (\omega - \omega_0) * t$$

Coupling Constants

- The energy levels of a nucleus will be affected by the spin state of nuclei nearby. The two nuclei that show this are said to be **coupled** to each other. This manifests in particular in cases where we have through bond connectivity:



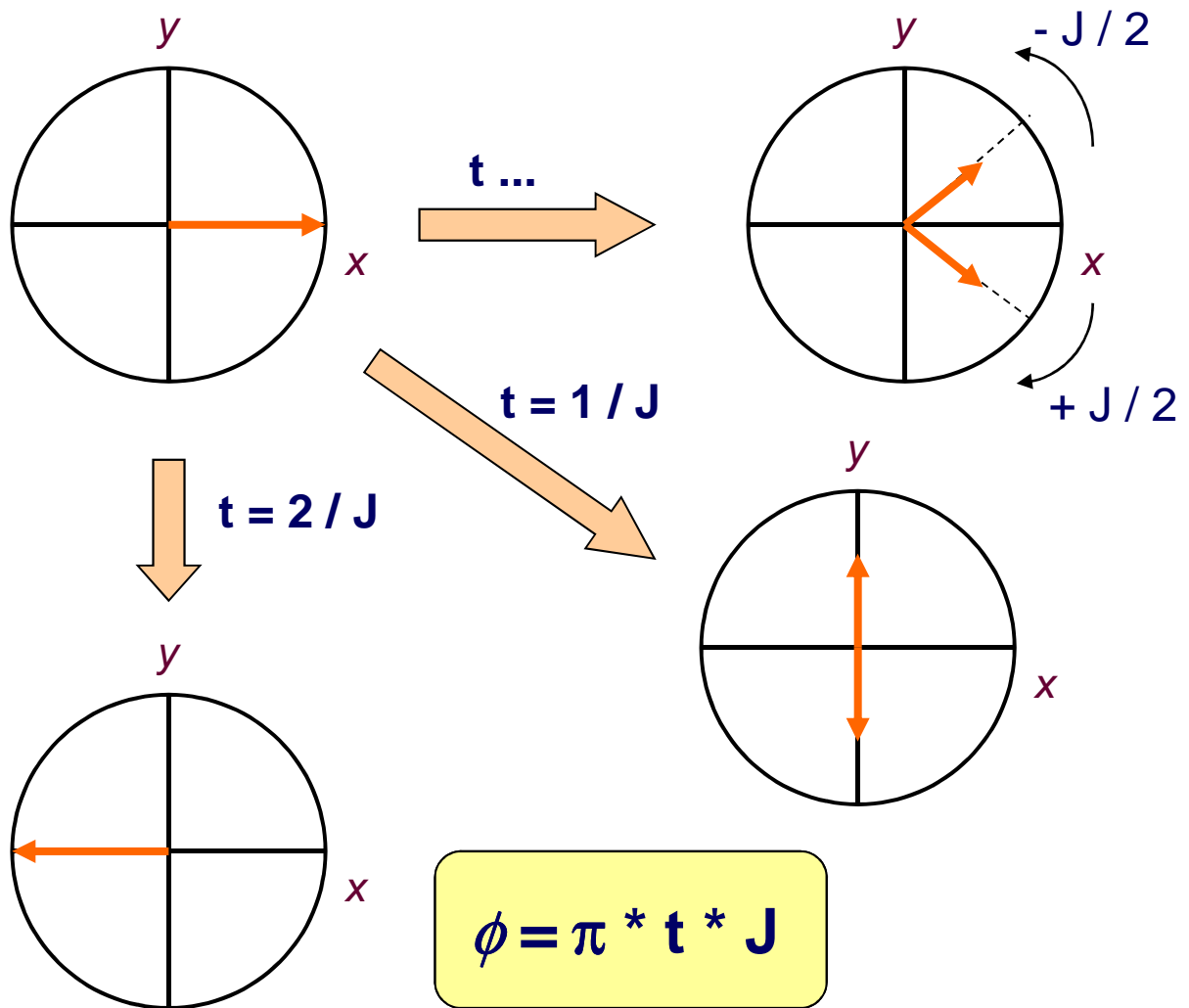
- Energy diagrams. Each spin now has two energy 'sub-levels' depending on the state of the spin it is coupled to:



- The magnitude of the separation is called **coupling constant** (**J**) and has units of Hz.
- Coupling patterns are crucial to identify spin systems in a molecule and to the determination of its chemical structure.

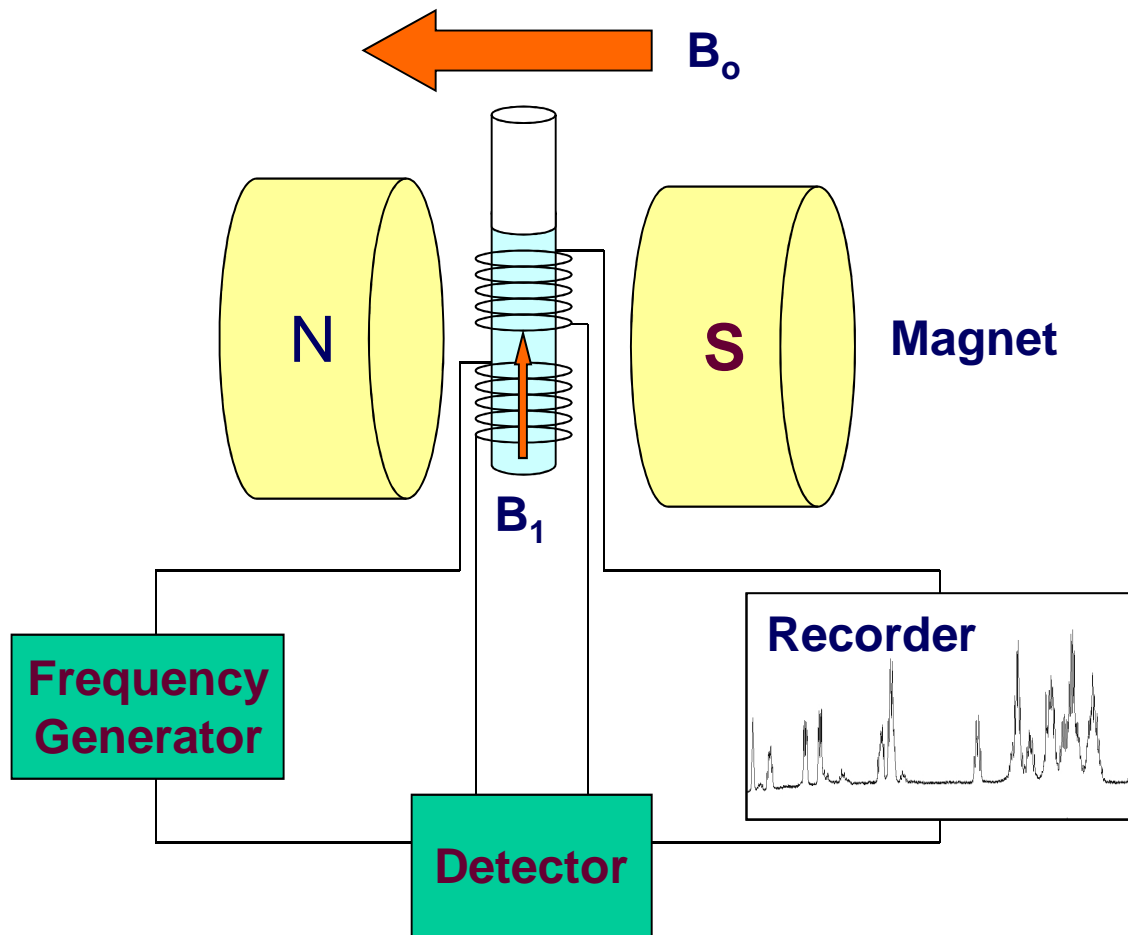
Couplings in the rotating frame

- We will consider an ensemble of spins **I** coupled to another spin **S** that is exactly at the resonant condition (ω of **B**₁ is ω_0), and again, only what goes on in the **<xy>** plane.
- The situation is analogous to what happened with chemical shift. In this case, since there are two new energy levels for the spin, we get two counter-rotating vectors. Their evolution will depend on the magnitude of **J**, not ω_0 :



NMR Instrumentation

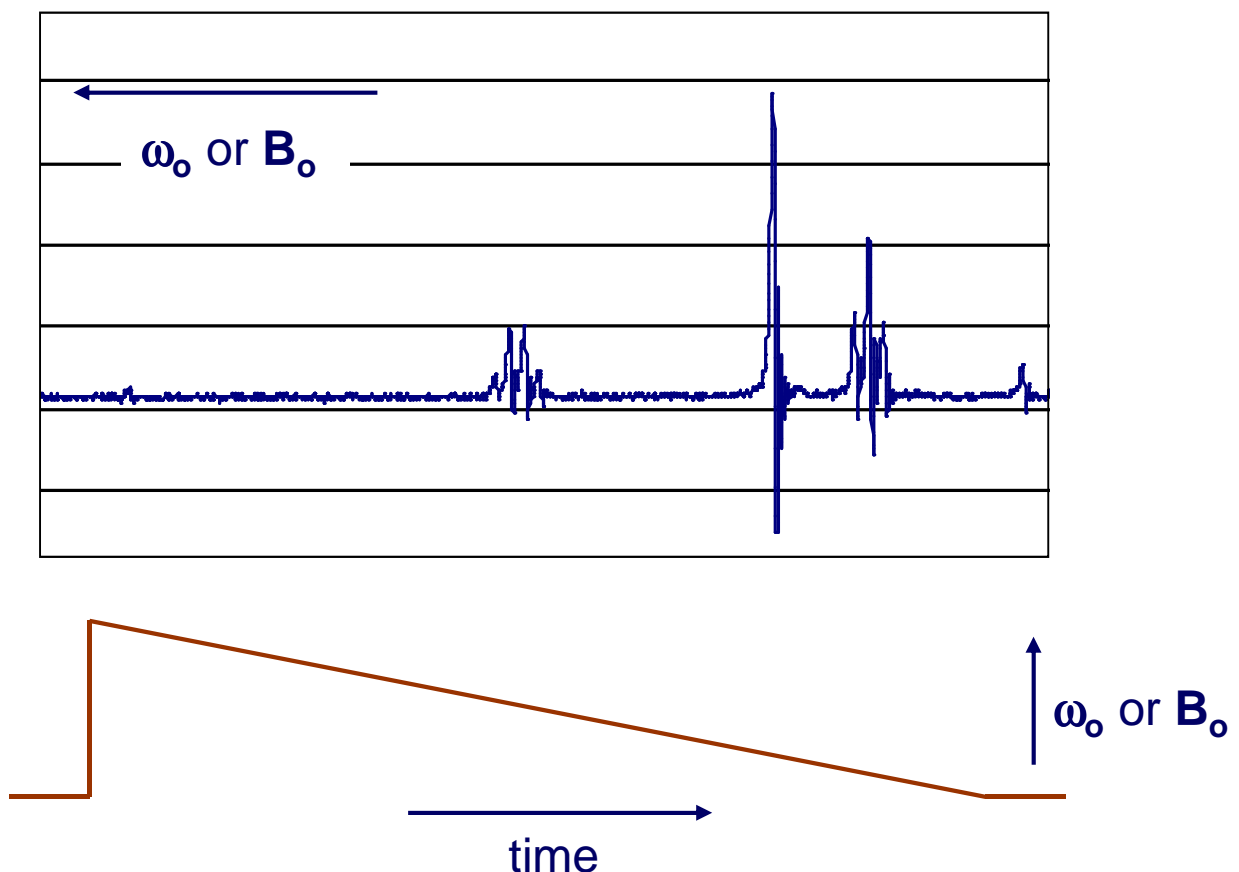
- An NMR machine is basically a big and expensive FM radio.



- **Magnet** - Normally superconducting. Some electromagnets and permanent magnets (EM-360, EM-390) still around.
- **Frequency generator** - Creates the alternating current (at ω_0) that induces B_1 . Continuous wave or pulsed.
- **Detector** - Subtracts the base frequency (a constant frequency very close to ω_0) to the output frequency. It is lower frequency and much easier to deal with.
- **Recorder** - XY plotter, oscilloscope, computer, etc., etc.

Continuous Wave excitation

- It's pretty *de mode*, and is only useful to obtain 1D spectra.
- The idea behind it is the same as in UV. We scan the frequencies continuously (or sweep the magnetic field, which has the same effect - $\omega = \gamma \mathbf{B}$), and record successively how the different components of \mathbf{M}_0 generate \mathbf{M}_{xy} at different frequencies (or magnetic fields).



- We get a time domain effect in the frequency spectrum (the famous *ringing*) because we cannot sweep slow enough.

Fourier Transform - Pulsed excitation

- The way every NMR instrument works today.
- The idea behind it is pretty simple. We have two ways of tuning a piano. One involves going key by key on the keyboard and recording each sound (or frequency). The other, kind of brutal for the piano, is to hit it with a sledge hammer and record all sounds at once.
- We then need something that has all frequencies at once. A short **pulse** of radiofrequency has these characteristics.
- To explain it, we use another black box mathematical tool, the **Fourier transform**: It is a transformation of information in the time domain to the frequency domain (and *vice versa*).

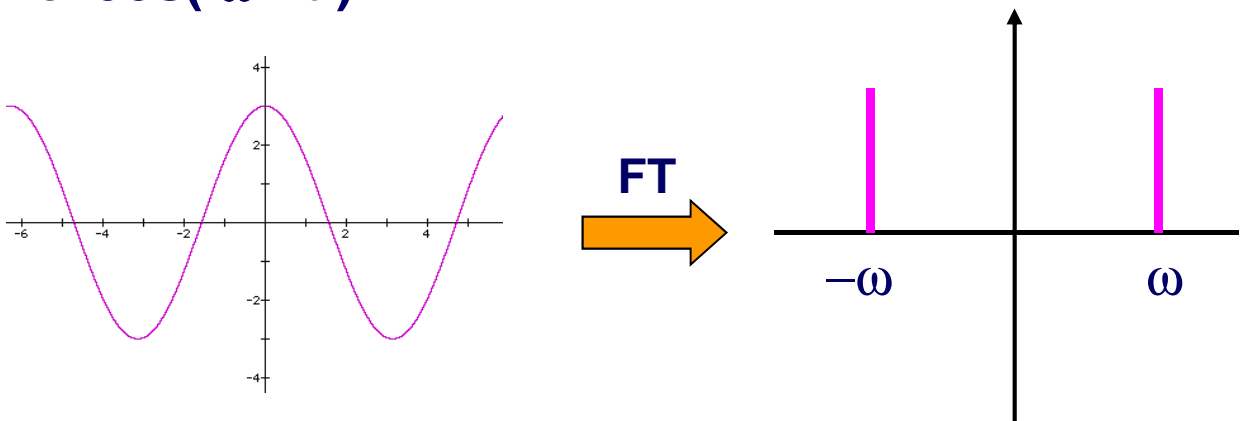
$$\mathbf{S}(\omega) = \int_{-\infty}^{\infty} \mathbf{S}(t) \mathbf{e}^{-i\omega t} dt$$
$$\mathbf{S}(t) = 1/2 \pi \int_{-\infty}^{\infty} \mathbf{S}(\omega) \mathbf{e}^{i\omega t} dt$$

- If our data in the time domain is periodical, it basically gives us its frequency components. Extremely useful in NMR, where all the signals are periodical.

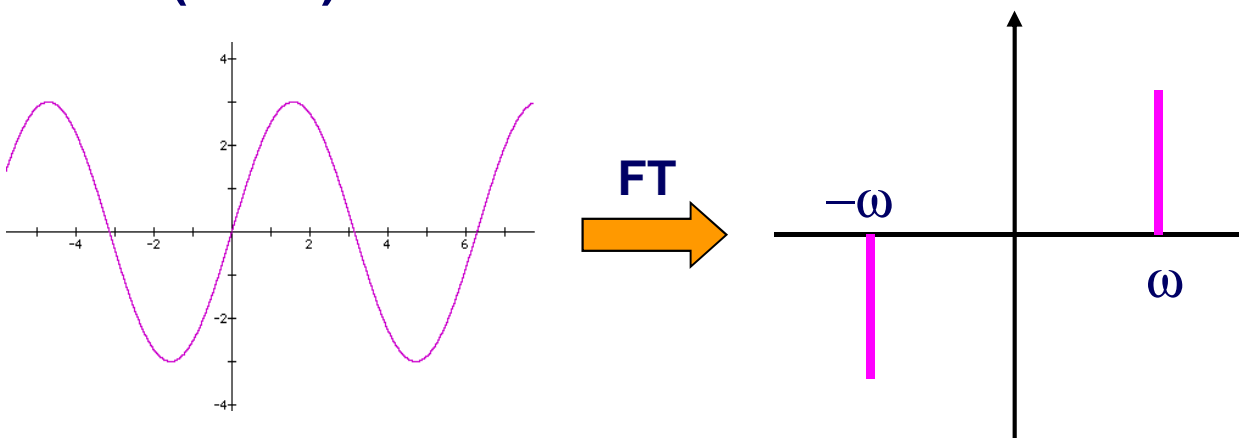
Fourier Transform of simple waves

- We can explain (or see) some properties of the FT with simple mathematical functions:

- For $\cos(\omega * t)$



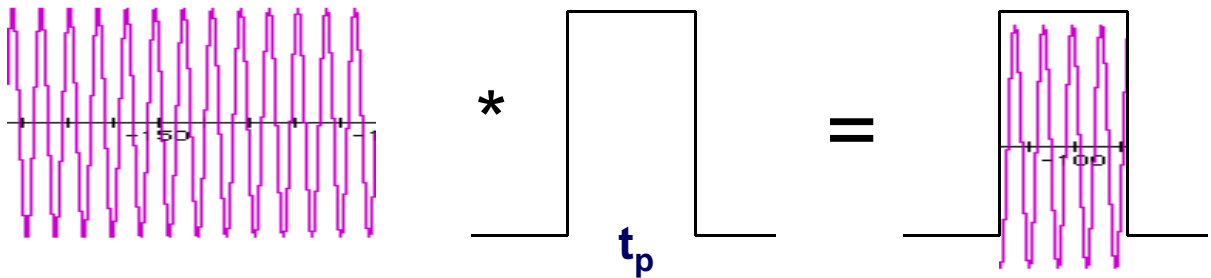
- For $\sin(\omega * t)$



- The cosines are said to give **absorptive** lines, while sines give **dispersive** lines. We'll refer to these particularly when talking about the **phase of the spectrum**. It is also important to remember this to understand **quadrature detection**.

Back to pulses

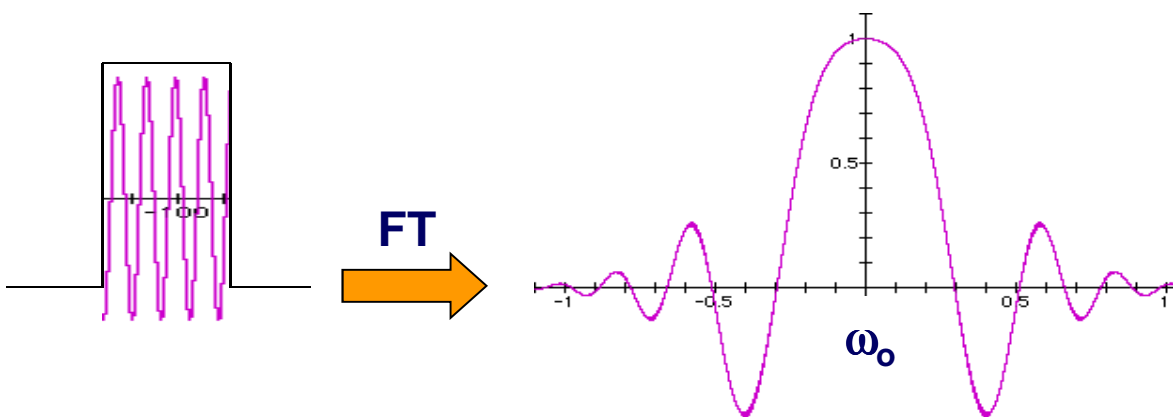
- Now that we 'master' the FT, we can see how pulses work. A radiofrequency pulse is a combination of a wave (cosine) of frequency ω_0 and a step function:



FT: 1 at $\omega_0 = \pm 1$

FT: $\frac{\sin(t_p \omega)}{t_p \omega}$ or $\text{sinc}(t_p \omega)$

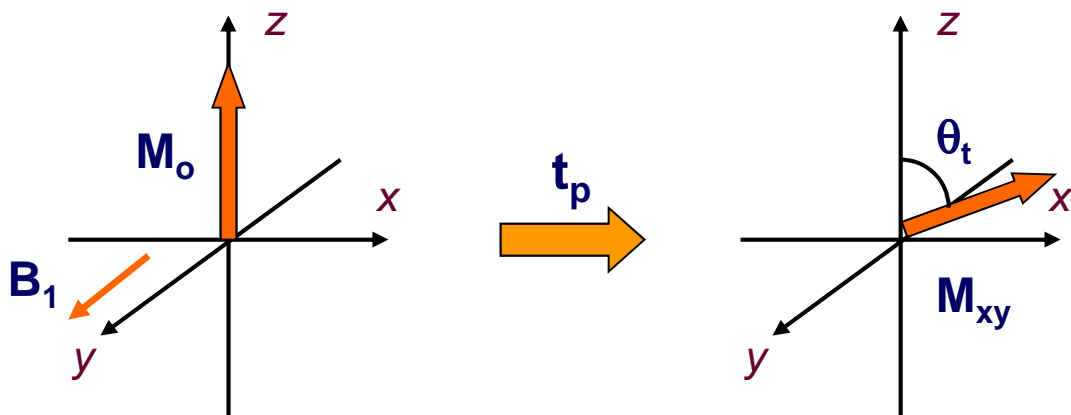
- This is the time domain shape of the pulse. To see the frequencies it really carry, we have to analyze it with FT:



- The result is a signal centered at ω_0 which covers a wide range of frequencies in both directions. Depending on the pulse width, we have wider (shorter t_p) or narrower (longer t_p) ranges. Remember that $f \propto 1/t$.

Pulse widths and tip angles

- The pulse width is not only associated with the frequency range (or sweep width), but it also indicates how long the excitation field \mathbf{B}_1 is on. Therefore, it is the time for which we will have a torque acting on the bulk magnetization \mathbf{M}_0 :

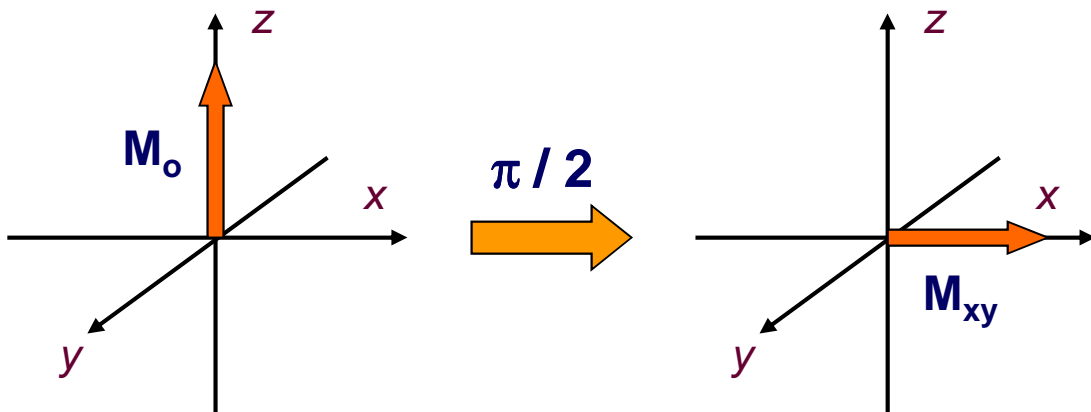


$$\theta_t = \gamma * t_p * B_1$$

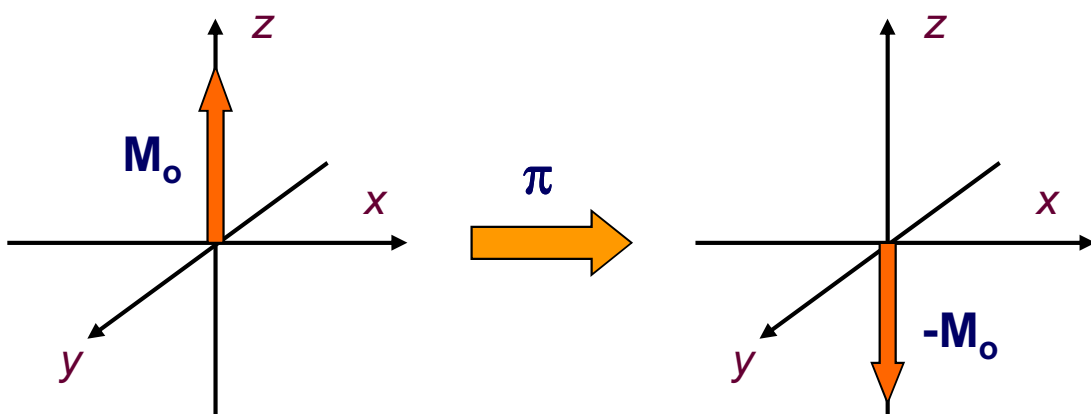
- As the pulse width for a certain flip angle will depend on the instrument (\mathbf{B}_1), we will therefore refer to them in terms of the rotation we want to obtain of the magnetization. Thus, we will have $\pi / 4$ (**45**), $\pi / 2$ (**90**), π (**180**), etc., etc., pulses.

Some useful pulses

- The most commonly used pulse is the $\pi/2$, because it puts as much magnetization as possible in the $\langle xy \rangle$ plane (more signal can be detected by the instrument):



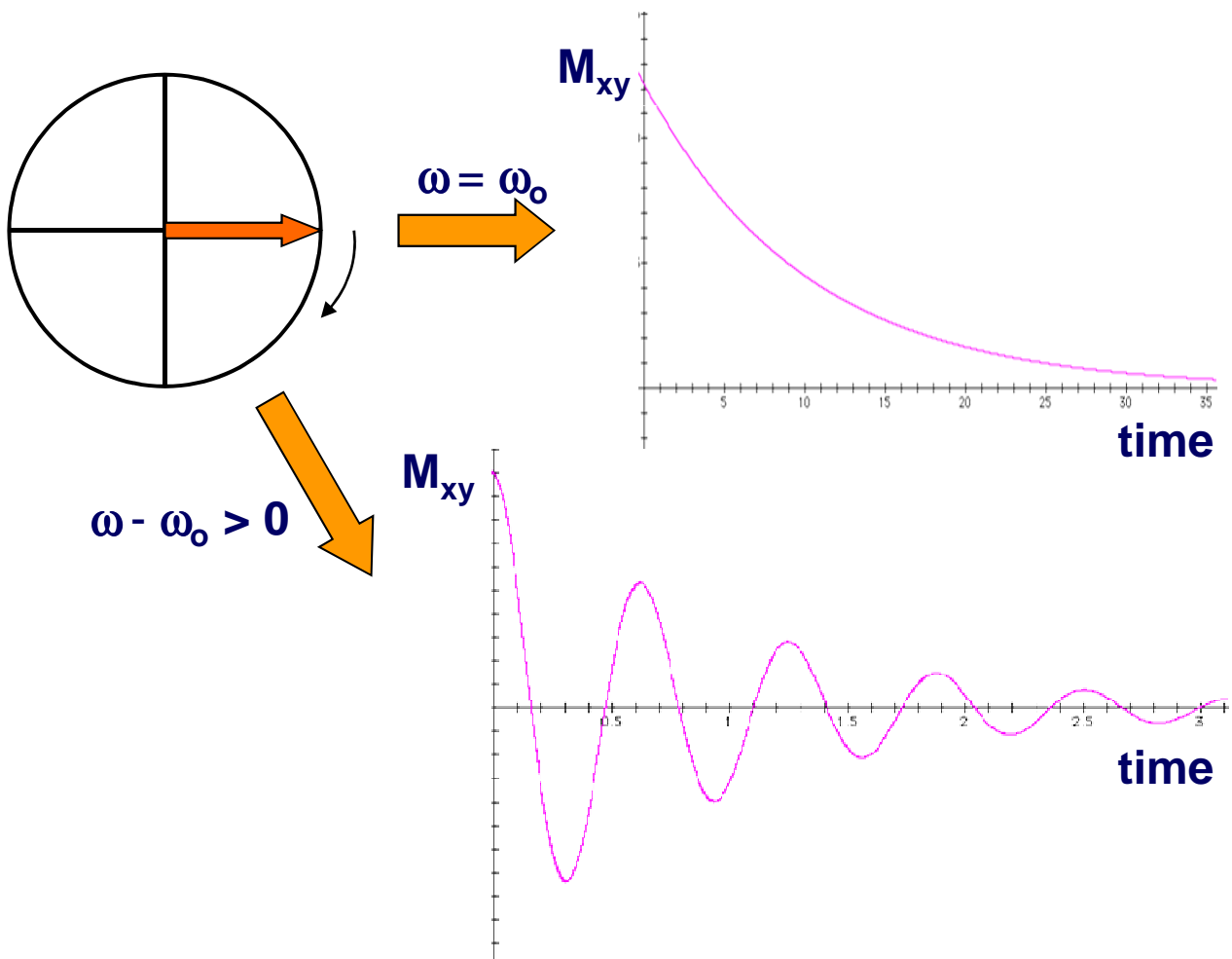
- Also important is the π pulse, which has the effect of inverting the populations of the spin system...



- With control of the spectrometer we can basically obtain any pulse width we want and flip angle we want.

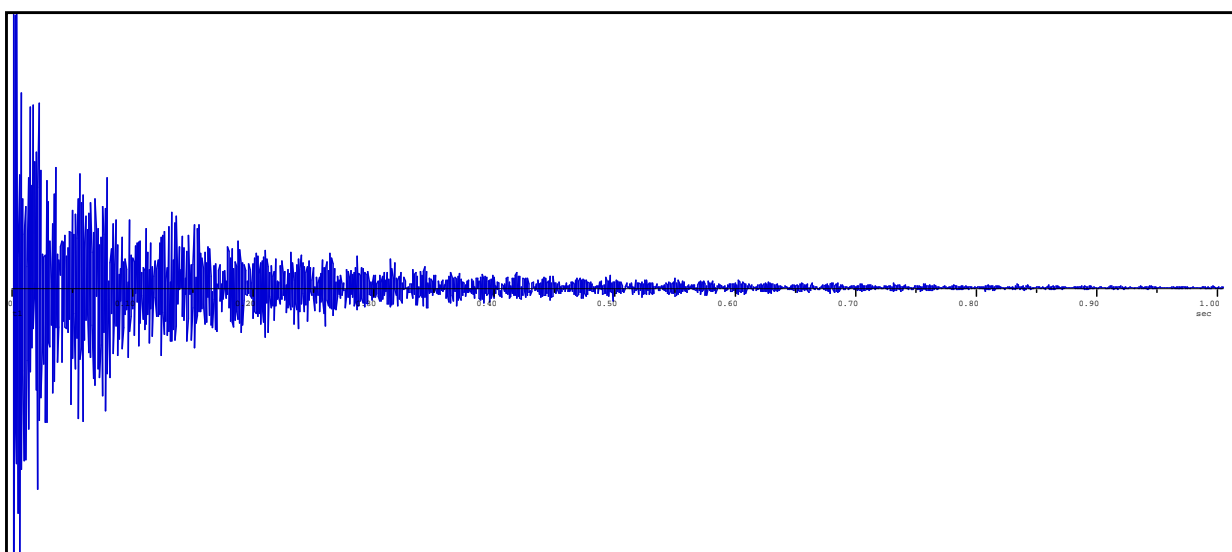
Free Induction Decay (FID)

- We forgot about the sample a bit. We are interested in the signal that appears in the receiver coil after putting the bulk magnetization in the $\langle xy \rangle$ plane ($\pi / 2$ pulse).
- We said earlier that the sample will go back to equilibrium (\mathbf{z}) precessing. In the rotating frame, the frequency of this precession is $\omega - \omega_0$. The relaxation of \mathbf{M}_0 in the $\langle xy \rangle$ plane is exponential (more next class). Therefore, the receiver coil detects a decaying sinusoidal signal (single spin type):



FID (continued)

- In a real sample we have hundreds of spin systems, all with frequencies different to that of B_1 (or *carrier frequency*). Since we used a pulse and excited all frequencies in our sample at once, we will see a combination of all of them in the receiver coil, called the *Free Induction Decay* (or *FID*):



- The FT of this signal gives us the NMR spectrum:

