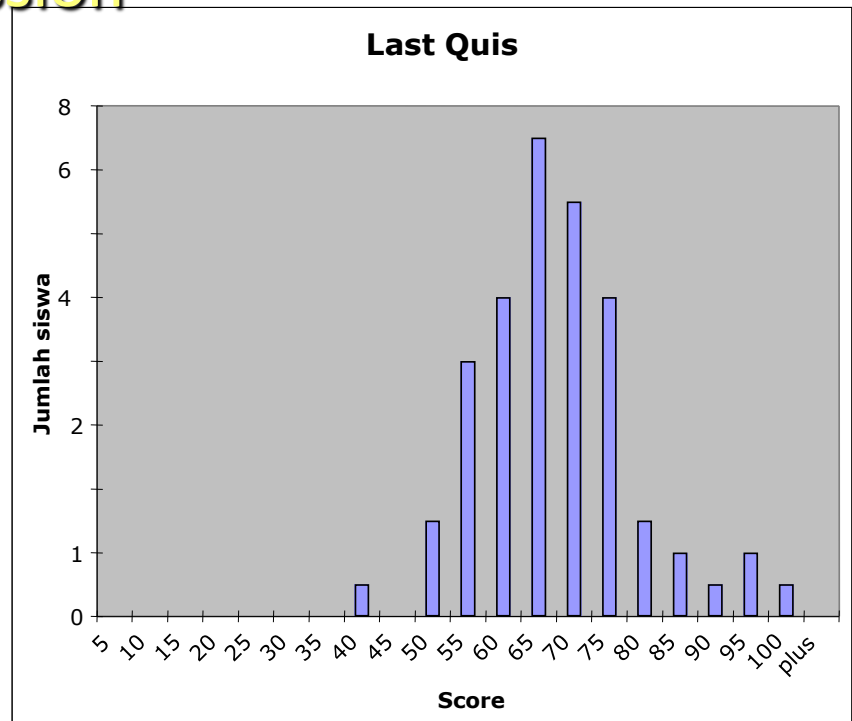


Tuesday, 3rd Nov 2009

Today's Topics:

- I really appreciate If all Of U can stand till the end of the course because of the language that U choose for U in this session
- Homework 6:
 - Sorry for delay (I've got sick)
- Last Quiz:
 - Average: 65%
- Now:
 - Linear momentum
 - Collision



Linear Momentum

- **Definition:** For a single particle, the linear momentum \mathbf{p} is defined as:

$$\mathbf{p} = m\mathbf{v}$$

(\mathbf{p} is a vector since \mathbf{v} is a vector).

So $p_x = mv_x$ etc.

- **Newton's 2nd Law:**

$$\mathbf{F} = m\mathbf{a} = m \frac{\Delta \mathbf{v}}{\Delta t} = \frac{\Delta(m\mathbf{v})}{\Delta t}$$



$$\mathbf{F} = \frac{\Delta \mathbf{p}}{\Delta t}$$

- Units of linear momentum are $kg \ m/s$.

Impulse-momentum theorem:

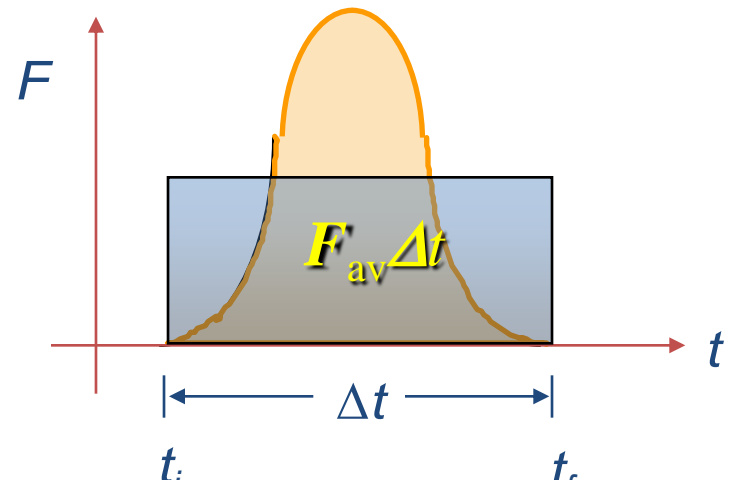
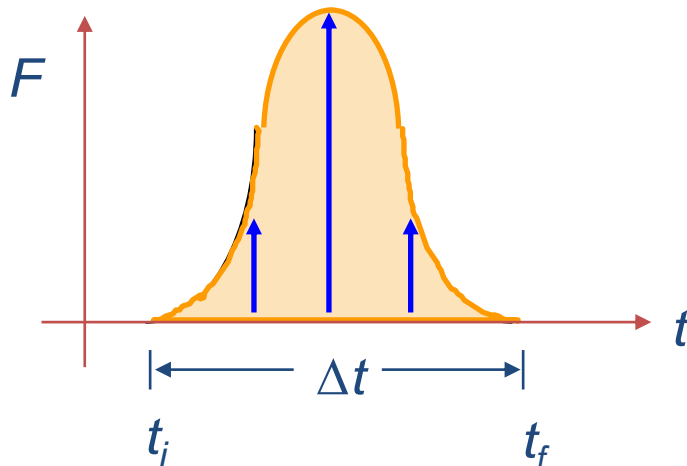
- The impulse of the force action on an object equals the change in momentum of the object:

$$F\Delta t = \Delta p = mv_f - mv_i$$

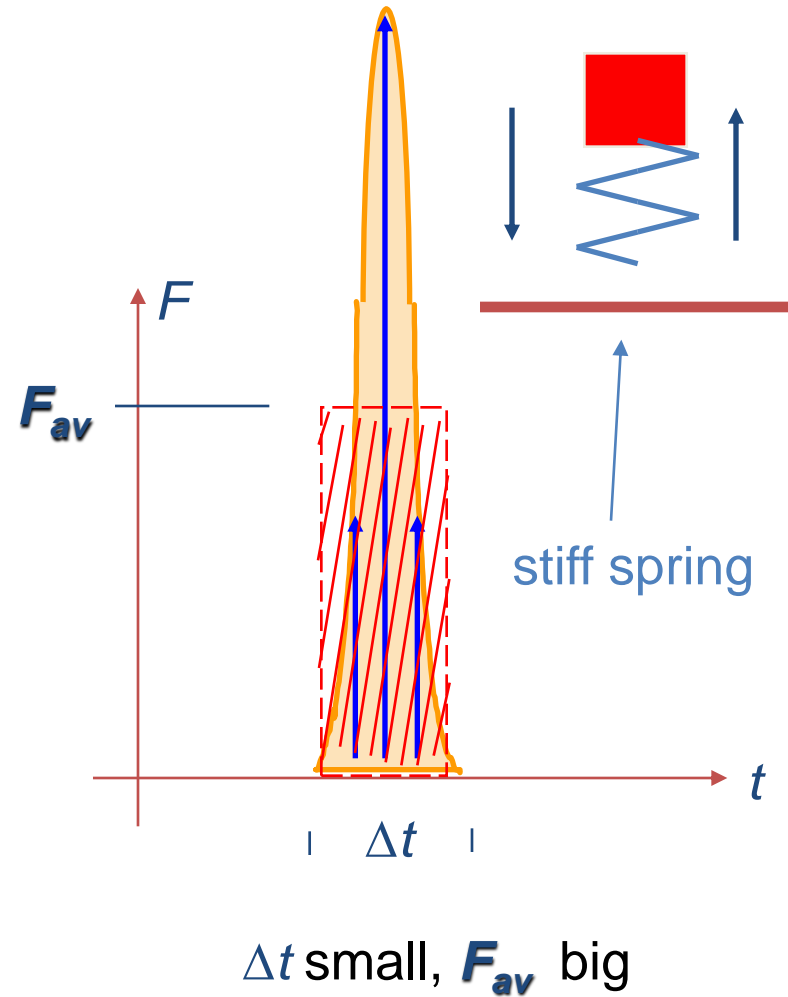
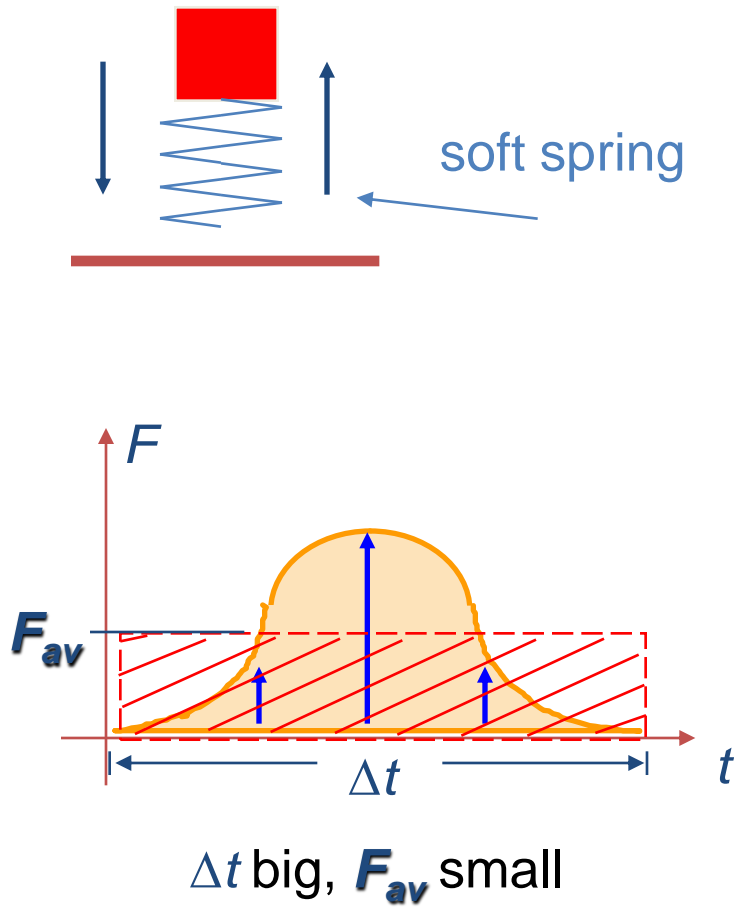
Impulse has units of *Ns*.

$$\text{Impulse} \equiv F\Delta t = \Delta p$$

- The impulse imparted by a force during the time interval Δt is equal to area under the force-time graph from beginning to the end of the time interval.



Average Force and Impulse



Momentum Conservation

The diagram illustrates the relationship between external force, momentum change, and momentum conservation. On the left, the equation $\mathbf{F}_{EXT} = \frac{\Delta \mathbf{p}}{\Delta t}$ is shown. A large blue arrow points from this equation to a central box containing the equation $\frac{\Delta \mathbf{p}}{\Delta t} = 0$. To the right of the box, another large blue arrow points from the box to the equation $\mathbf{F}_{EXT} = 0$. Below the central box, a large blue arrow points downwards, indicating the result of the conservation condition.

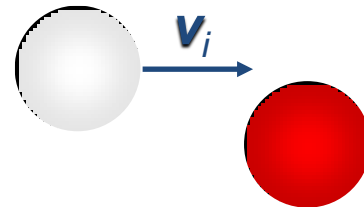
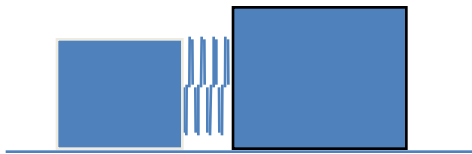
- The concept of **momentum conservation** is one of the most fundamental principles in physics.
- This is a component (vector) equation.
 - We can apply it to any direction in which there is no external force applied.
- You will see that we often have momentum conservation even when energy is not conserved.

Elastic vs. Inelastic Collisions

- A collision is said to be *elastic* when energy as well as momentum is conserved before and after the collision.

$$K_{\text{before}} = K_{\text{after}}$$

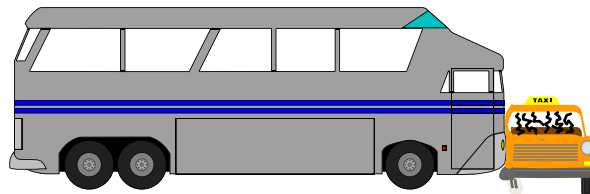
- Carts colliding with a spring in between, billiard balls, etc.



- A collision is said to be *inelastic* when energy is not conserved before and after the collision, but momentum is conserved.

$$K_{\text{before}} \neq K_{\text{after}}$$

- ← Car crashes, collisions where objects stick together, etc.



Inelastic collision in 1-D: Example 1

- A block of mass M is initially at rest on a frictionless horizontal surface. A bullet of mass m is fired at the block with a muzzle velocity (speed) v . The bullet lodges in the block, and the block ends up with a speed V . In terms of m , M , and V :
 - What is the momentum of the bullet with speed v ?
 - What is the initial energy of the system ?
 - What is the final energy of the system ?
 - Is energy conserved ?

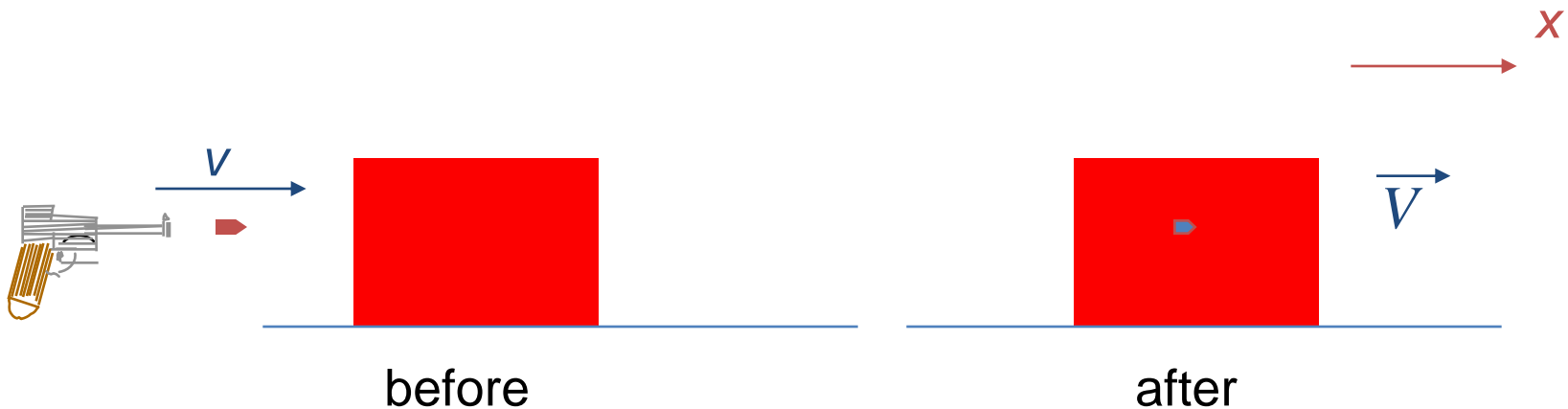


Example 1...

- Consider the bullet & block as a system. After the bullet is shot, there are no external forces acting on the system in the x -direction

Momentum is conserved in the x direction !

$$\begin{aligned} - P_{x,\text{before}} &= P_{x,\text{after}} \\ - mv &= (M+m) V \end{aligned} \quad \Rightarrow \quad v = \left(\frac{M+m}{m} \right) V$$



$$v = \left(\frac{M + m}{m} \right) V$$

Example 1...

- Now consider the energy of the system before and after:

- Before:

- After: $E_B = \frac{1}{2} m v^2 = \frac{1}{2} m \left(\frac{M + m}{m} \right)^2 V^2 = \frac{1}{2} \left(\frac{M + m}{m} \right) (M + m) V^2$

- So

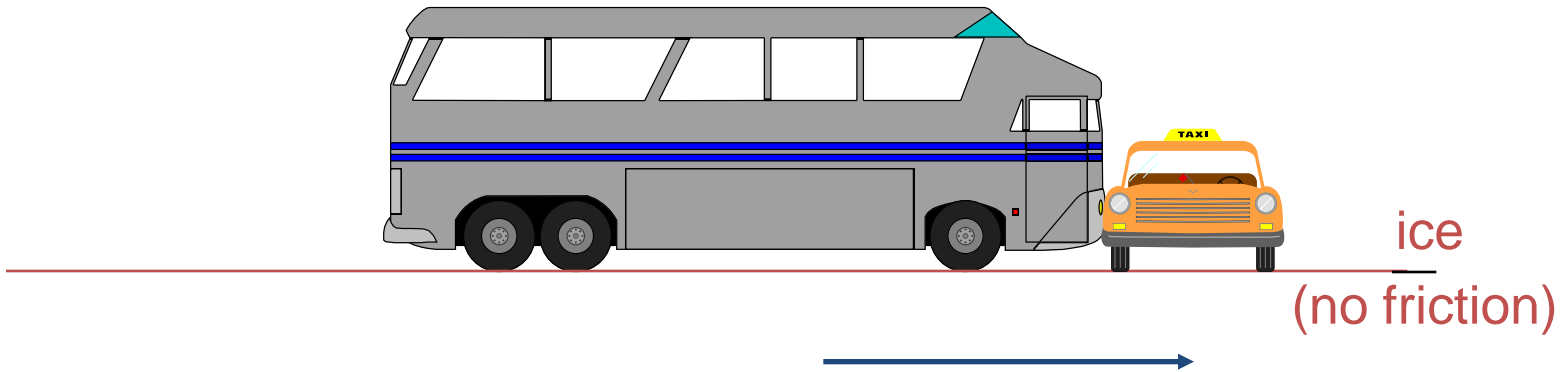
$$E_A = \frac{1}{2} (M + m) V^2$$

$$E_A = \left(\frac{m}{M + m} \right) E_B$$

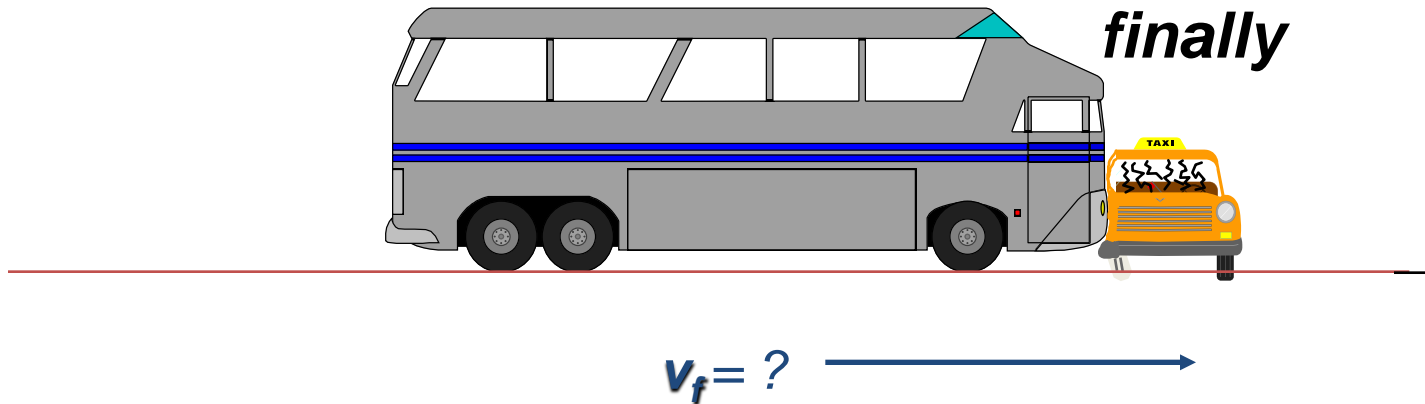
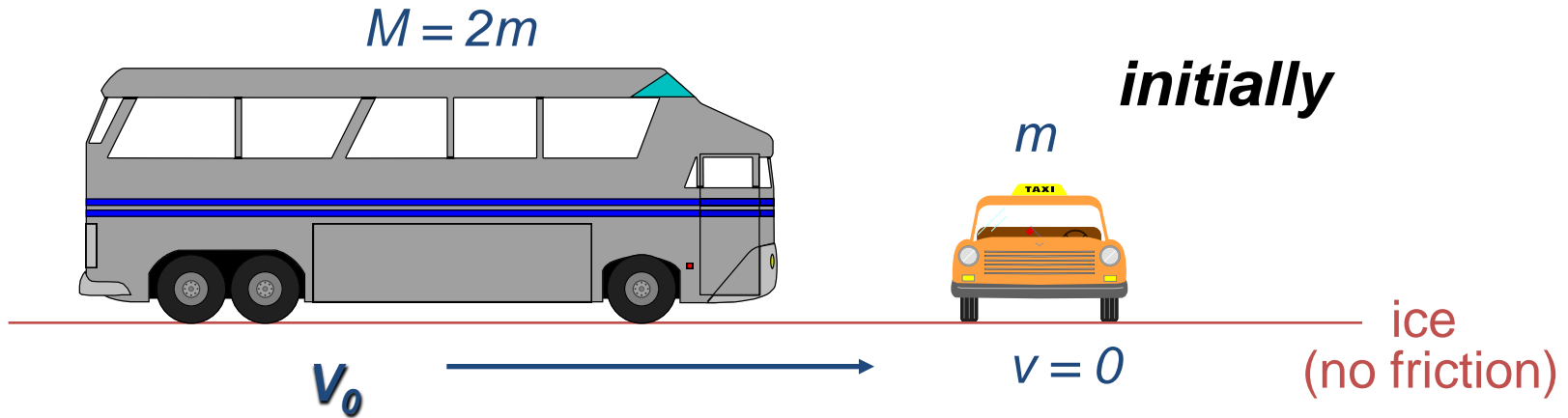
Energy is NOT conserved (friction stopped the bullet)
However momentum was conserved, and this was useful.

Inelastic Collision in 1-D

Winter in Storrs



Inelastic Collision in 1-D



- $V_f =$ A) 0 B) $V_0/2$ C) $2V_0/3$ D) $3V_0/2$ E) $2V_0$

Inelastic Collision in 1-D

Use conservation of momentum to find \mathbf{v} after the collision.

Before the collision:

$$\mathbf{P}_i = M\mathbf{V}_o + m(0)$$

After the collision:

$$\mathbf{P}_f = (M + m)\mathbf{V}_f$$

Conservation of momentum:

$$\begin{aligned} \mathbf{P}_i &= \mathbf{P}_f \\ M\mathbf{V}_o &= (M + m)\mathbf{V}_f \end{aligned}$$

$$\mathbf{V}_f = \frac{M}{(M + m)}\mathbf{V}_o = \frac{2m}{(2m + m)}\mathbf{V}_o = \frac{2}{3}\mathbf{V}_o$$

C) $2V_o/3$

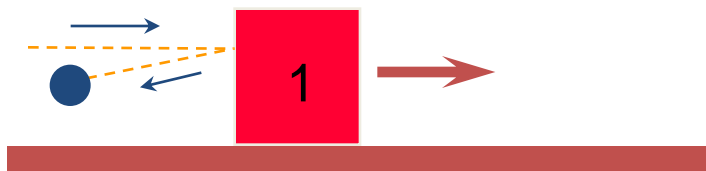
Momentum Conservation

- Two balls of equal mass are thrown horizontally with the same initial velocity. They hit identical stationary boxes resting on a frictionless horizontal surface.
- The ball hitting box 1 bounces back, while the ball hitting box 2 gets stuck.
 - Which box ends up moving fastest ?

(a) Box 1

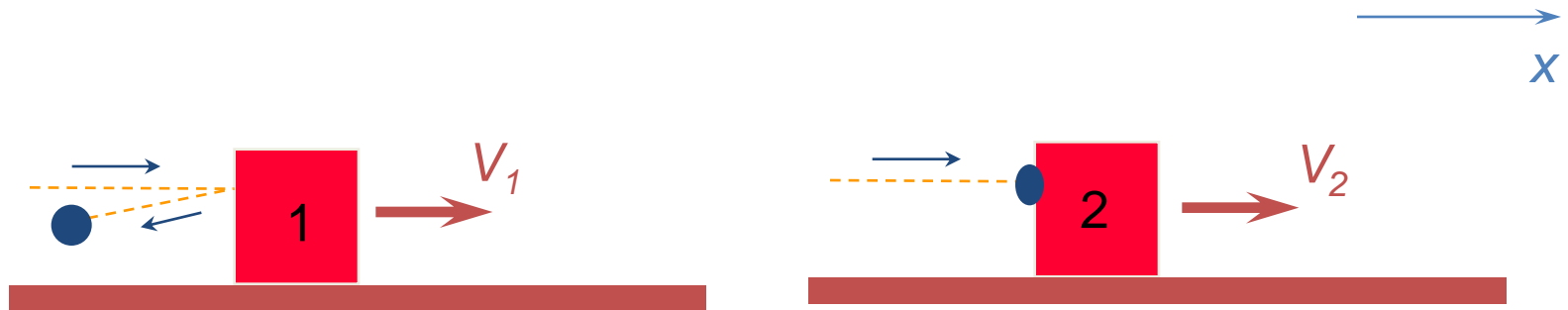
(b) Box 2

(c) same



Momentum Conservation

- Since the total external force in the x-direction is zero, momentum is conserved along the x-axis.
- In both cases the initial momentum is the same (mv of ball).
- In case 1 the ball has **negative** momentum after the collision, hence the box must have more **positive** momentum if the total is to be conserved.
- The speed of the box in case 1 is biggest !



Momentum Conservation

$$mv = MV_1 - mv'$$

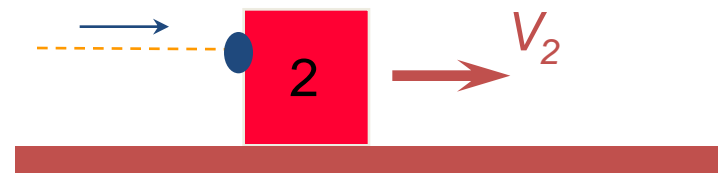
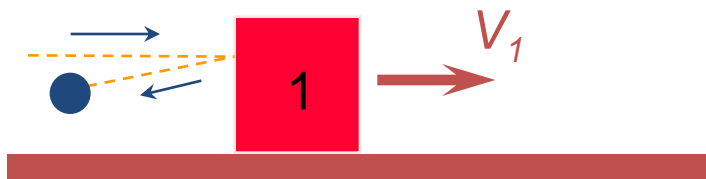
$$\Rightarrow V_1 = (mv + mv') / M$$

$$mv = (M+m)V_2$$

$$\Rightarrow V_2 = mv / (M+m)$$

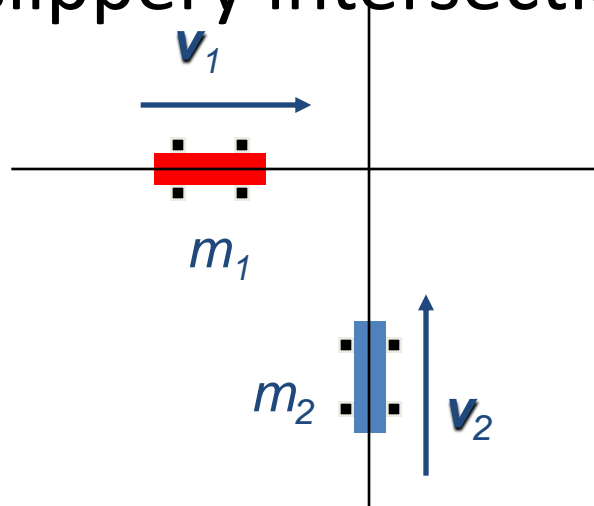
V_1 numerator is bigger and its denominator is smaller than that of V_2 .

$$\Rightarrow V_1 > V_2$$

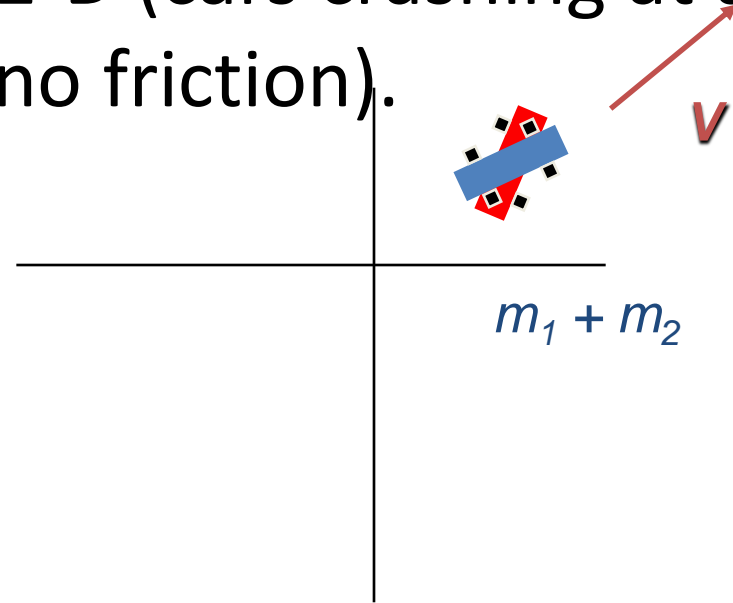


Inelastic collision in 2-D

- Consider a collision in 2-D (cars crashing at a slippery intersection...no friction).



before



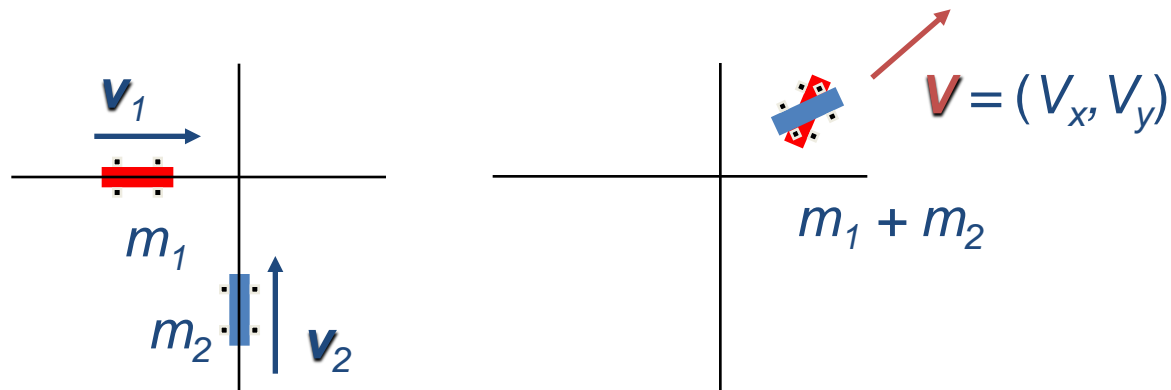
after

Inelastic collision in 2-D...

- There are no net external forces acting.
 - Use momentum conservation for both components.

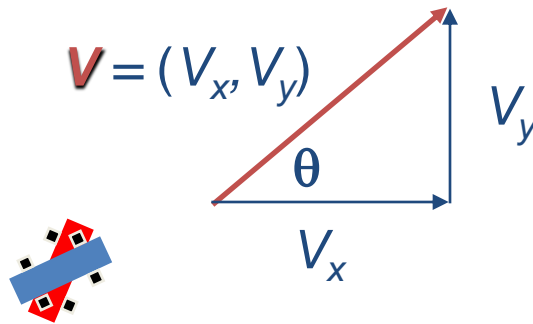
$$P_{x,a} = P_{x,b} \Rightarrow m_1 v_1 = (m_1 + m_2) V_x \Rightarrow V_x = \frac{m_1}{(m_1 + m_2)} v_1$$

$$P_{y,a} = P_{y,b} \Rightarrow m_2 v_2 = (m_1 + m_2) V_y \Rightarrow V_y = \frac{m_2}{(m_1 + m_2)} v_2$$



Inelastic collision in 2-D...

- So we know all about the motion after the collision !



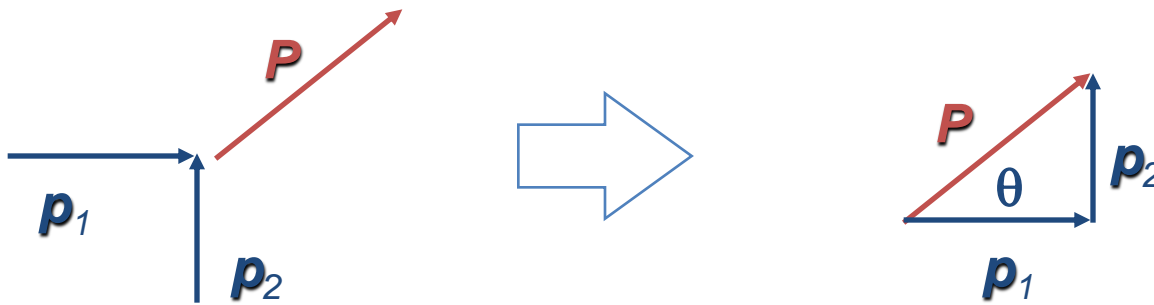
$$V_x = \frac{m_1}{(m_1 + m_2)} v_1$$

$$V_y = \frac{m_2}{(m_1 + m_2)} v_2$$

$$\tan \theta = \frac{V_y}{V_x} = \frac{m_2 v_2}{m_1 v_1} = \frac{p_2}{p_1}$$

Inelastic collision in 2-D...

- We can see the same thing using vectors:



$$\tan \theta = \frac{p_2}{p_1}$$

Explosion (inelastic un-collision)

Before the explosion:



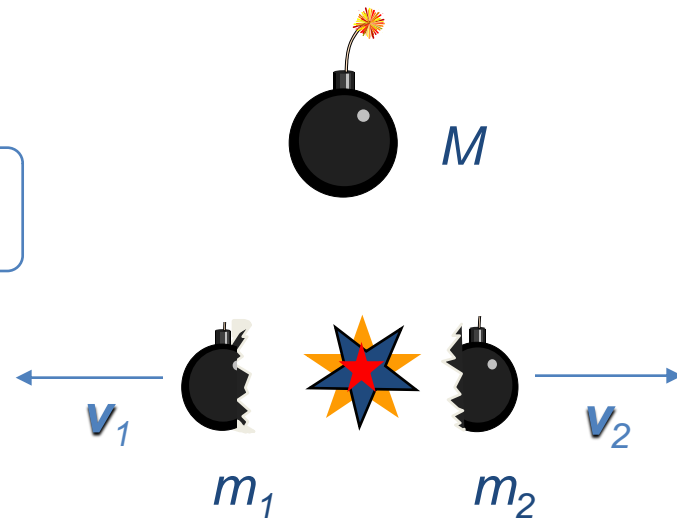
After the explosion:



Explosion...

- No external forces, so \mathbf{P} is conserved.
- Initially: $\mathbf{P} = 0$
- Finally: $\mathbf{P} = m_1\mathbf{v}_1 + m_2\mathbf{v}_2 = 0$

$$m_1\mathbf{v}_1 = -m_2\mathbf{v}_2$$



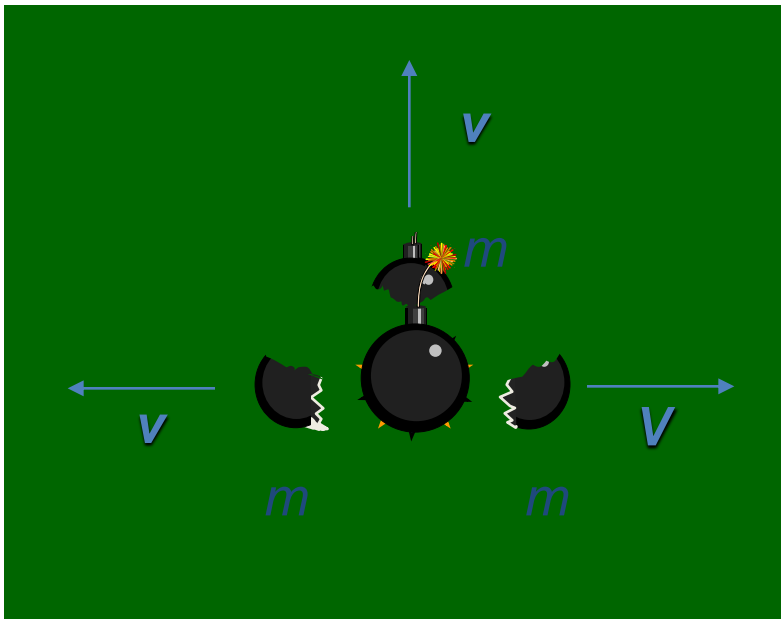
Center of Mass

- A bomb explodes into 3 identical pieces. Which of the following configurations of velocities is possible?

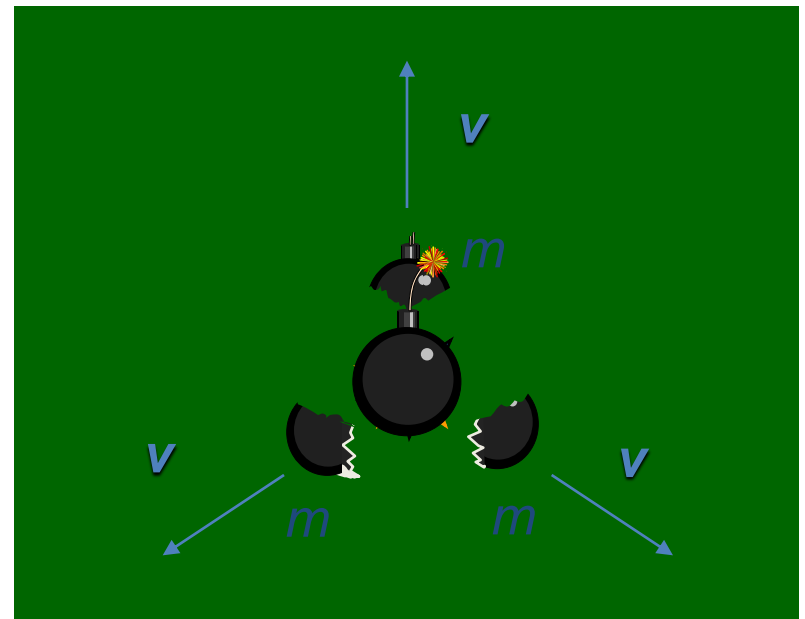
(a) 1

(b) 2

(c) *both*



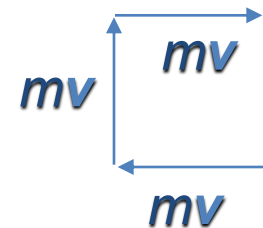
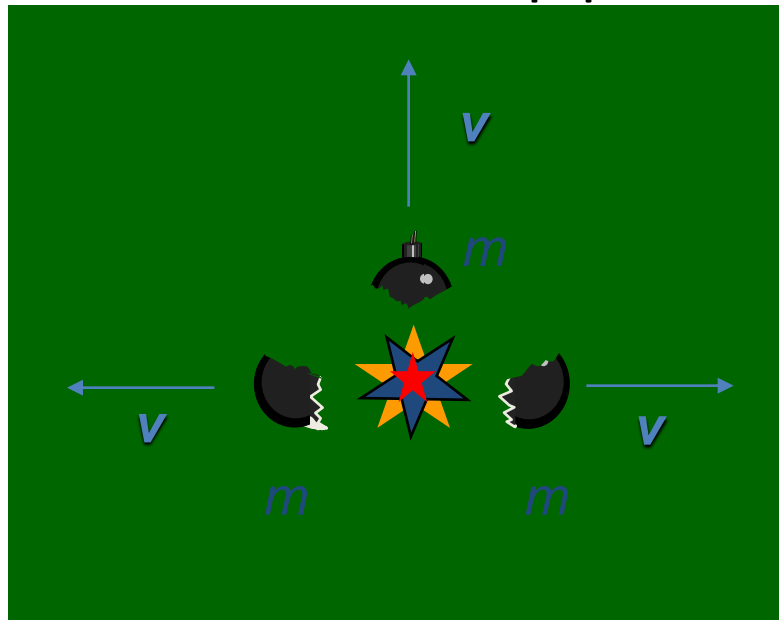
(1)



(2)

Solution

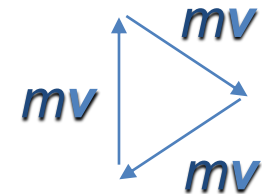
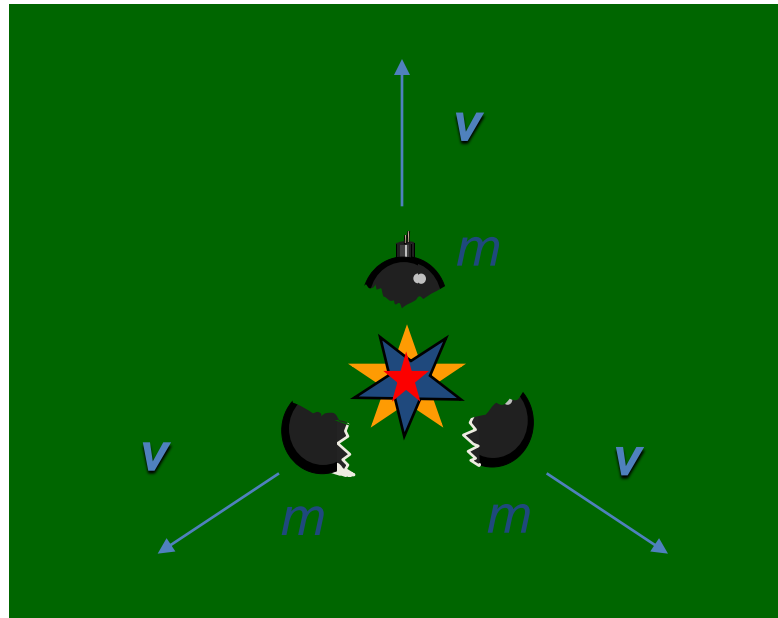
- No external forces, so \mathbf{P} must be conserved.
- Initially: $\mathbf{P} = 0$
- In explosion (1) there is nothing to balance the upward momentum of the top piece so $\mathbf{P}_{final} \neq 0$.



(1)

Solution

- No external forces, so \mathbf{P} must be conserved.
- All the momenta cancel out.
- $\mathbf{P}_{final} = 0$.

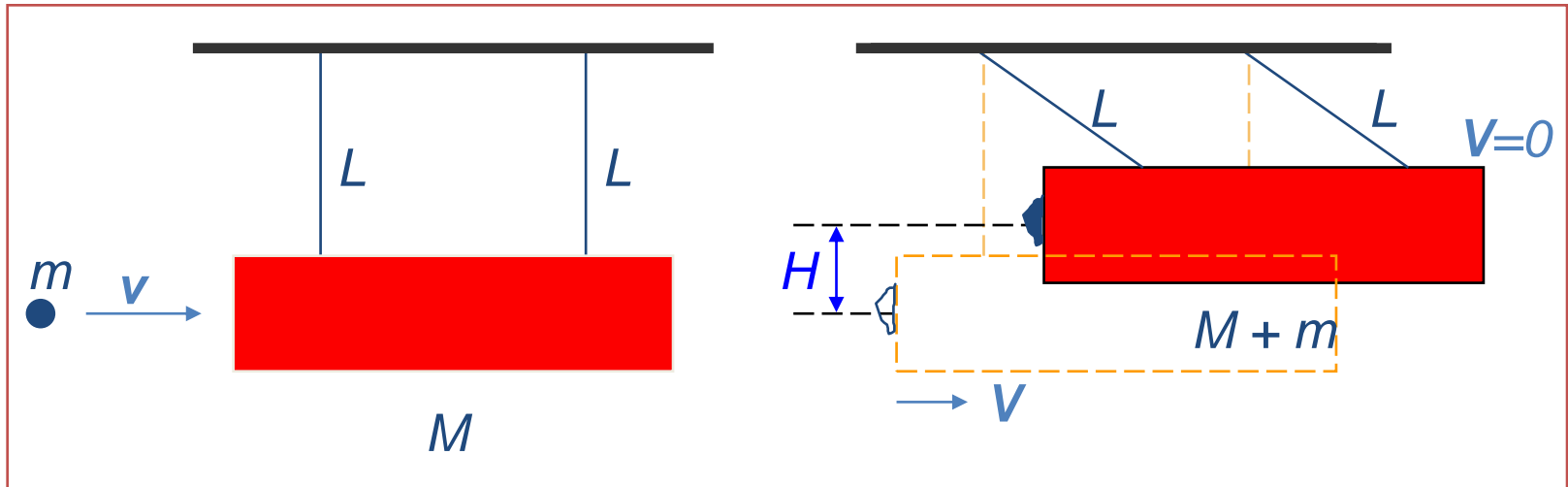


(2)

Comment on Energy Conservation

- We have seen that the total kinetic energy of a system undergoing an inelastic collision is not conserved.
 - Energy is lost:
 - Heat (bomb)
 - Bending of metal (crashing cars)
- Kinetic energy **is not** conserved since **work** is done during the collision !
- Momentum along a certain direction **is** conserved when there are **no external forces** acting in this direction.
 - In general, easier to satisfy than energy conservation.

Ballistic Pendulum



- A projectile of mass m moving horizontally with speed v strikes a stationary mass M suspended by strings of length L . Subsequently, $m + M$ rise to a height of H .

Given H , what is the initial speed v of the projectile?

Ballistic Pendulum...

- Two stage process:
 1. m collides with M , inelastically. Both M and m then move together with a velocity V (before having risen significantly).
 2. M and m rise a height H , conserving energy E . (no non-conservative forces acting after collision)

Ballistic Pendulum...

- Stage 1: Momentum is conserved

in x-direction: $mv = (m + M)V$

$$V = \left(\frac{m}{m + M} \right) v$$

- Stage 2: Energy is conserved

$$(E_I = E_F)$$

$$\frac{1}{2}(m + M)V^2 = (m + M)gH$$

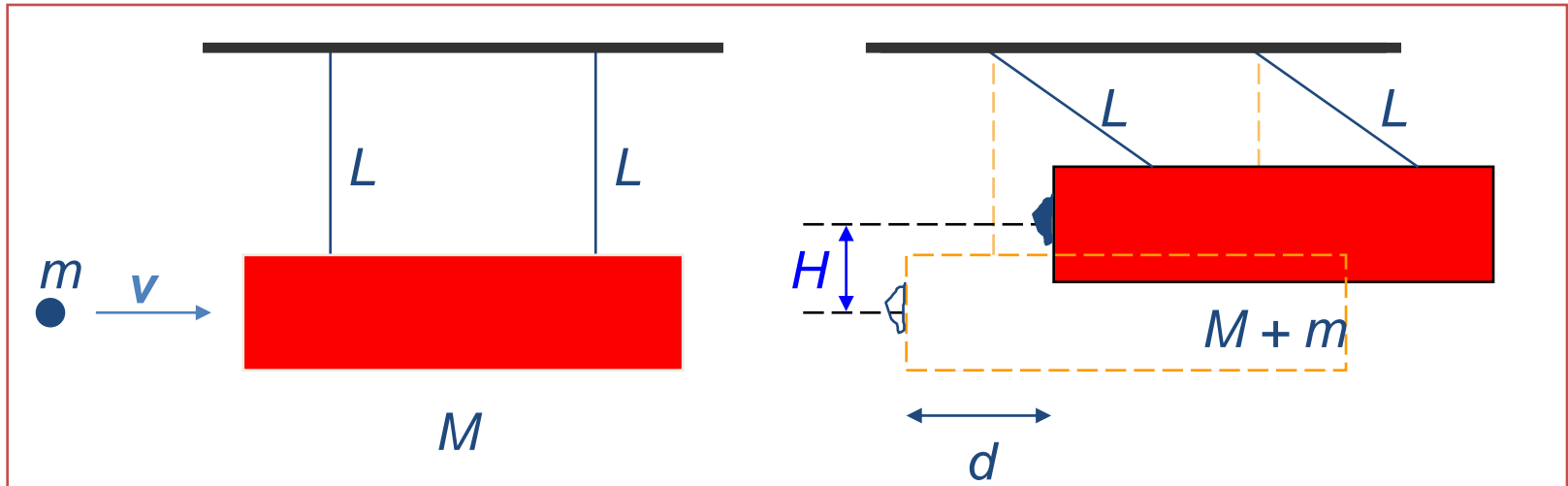


$$V^2 = 2gH$$

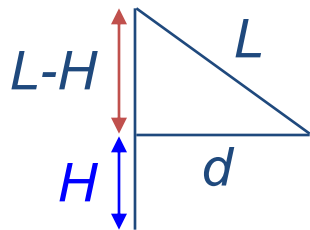
Eliminating V gives:

$$v = \left(1 + \frac{M}{m} \right) \sqrt{2gH}$$

Ballistic Pendulum



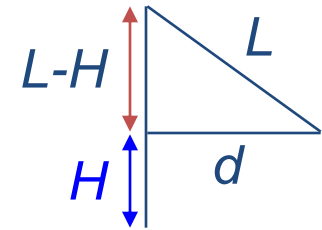
- If we measure the forward displacement d , not H :



$$L^2 = d^2 + (L - H)^2$$

$$H = L - \sqrt{L^2 - d^2}$$

Ballistic Pendulum



$$H = L - \sqrt{L^2 - d^2}$$
$$= L - L\sqrt{1 - \frac{d^2}{L^2}} \approx L - L\left(1 - \frac{d^2}{2L^2}\right) \approx \frac{d^2}{2L} \quad \text{for } \frac{d}{L} \ll 1$$

$$v = \left(1 + \frac{M}{m}\right) \sqrt{2gH}$$



$$v = \left(1 + \frac{M}{m}\right) \cdot d \cdot \sqrt{\frac{g}{L}}$$

for $d \ll L$

- See Cutnell :

p.

Number :

please submit by your attach files as usual
before early wed next week (11th Nov, 2009)

- All of assignment is not an easy homework, so
please do early