

# William Stallings

# Computer Organization

# and Architecture

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Chapter 12

Reduced Instruction  
Set Computers

# Major Advances in Computers(1)

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## ⌘ The family concept

- ☒ IBM System/360 1964
- ☒ DEC PDP-8
- ☒ Separates architecture from implementation

## ⌘ Microporgrammed control unit

- ☒ Idea by Wilkes 1951
- ☒ Produced by IBM S/360 1964

## ⌘ Cache memory

- ☒ IBM S/360 model 85 1969

# Major Advances in Computers(2)

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## ⌘ Solid State RAM

↗(See memory notes)

## ⌘ Microprocessors

↗Intel 4004 1971

## ⌘ Pipelining

↗Introduces parallelism into fetch execute cycle

## ⌘ Multiple processors

# The Next Step - RISC

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## ⌘ Reduced Instruction Set Computer

### ⌘ Key features

- ☒ Large number of general purpose registers
- ☒ or use of compiler technology to optimize register use
- ☒ Limited and simple instruction set
- ☒ Emphasis on optimising the instruction pipeline

# Comparison of processors

	<u>CISC</u>			<u>RISC</u>		<u>Superscalar</u>	
#	IBM	DEC VAX	Intel			IBM	Intel
#	370/168	11/780	486	88000	R4000	RS/6000	80960
#	1973	1978	1989	1988	1991	1990	1989
#	No. of instruction						
#	208	303	235	51	94	184	62
#	Instruction size (octets)						
#	2-6	2-57	1-11	4	32	4	4 or 8
#	Addressing modes						
#	4	22	11	3	1	2	11
#	GP Registers						
#	16	16	8	32	32	32	23-256
#	Control memory (k bytes) (microprogramming)			0	0	0	0
#	420	480	246				

# Driving force for CISC

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- # Software costs far exceed hardware costs
- # Increasingly complex high level languages
- # Semantic gap
- # Leads to:
  - ☒ Large instruction sets
  - ☒ More addressing modes
  - ☒ Hardware implementations of HLL statements
    - ☒ e.g. CASE (switch) on VAX

# Intention of CISC

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- ⌘ Ease compiler writing
- ⌘ Improve execution efficiency
  - ☒ Complex operations in microcode
- ⌘ Support more complex HLLs

# Execution Characteristics

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- # Operations performed
- # Operands used
- # Execution sequencing
- # Studies have been done based on programs written in HLLs
- # Dynamic studies are measured during the execution of the program

# Operations

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- ⌘ Assignments

- ↗ Movement of data

- ⌘ Conditional statements (IF, LOOP)

- ↗ Sequence control

- ⌘ Procedure call-return is very time consuming

- ⌘ Some HLL instruction lead to many machine code operations

# Relative Dynamic Frequency

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	Dynamic Occurrence		Machine Instruction (Weighted)		Memory Reference (Weighted)	
	Pascal	C	Pascal	C	Pascal	C
Assign	45	38	13	13	14	15
Loop	5	3	42	32	33	26
Call	15	12	31	33	44	45
If	29	43	11	21	7	13
GoTo	-	3	-	-	-	-
Other	6	1	3	1	2	1

# Operands

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- ⌘ Mainly local scalar variables
- ⌘ Optimisation should concentrate on accessing local variables

	Pascal	C	Average
Integer constant	16	23	20
Scalar variable	58	53	55
Array/structure	26	24	25

# Procedure Calls

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- ⌘ Very time consuming
- ⌘ Depends on number of parameters passed
- ⌘ Depends on level of nesting
- ⌘ Most programs do not do a lot of calls followed by lots of returns
- ⌘ Most variables are local
- ⌘ (c.f. locality of reference)

# Implications

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- ⌘ Best support is given by optimising most used and most time consuming features
- ⌘ Large number of registers
  - ↗ Operand referencing
- ⌘ Careful design of pipelines
  - ↗ Branch prediction etc.
- ⌘ Simplified (reduced) instruction set

# Large Register File

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## ⌘ Software solution

- ☒ Require compiler to allocate registers
- ☒ Allocate based on most used variables in a given time
- ☒ Requires sophisticated program analysis

## ⌘ Hardware solution

- ☒ Have more registers
- ☒ Thus more variables will be in registers

# Registers for Local Variables

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- # Store local scalar variables in registers
- # Reduces memory access
- # Every procedure (function) call changes locality
- # Parameters must be passed
- # Results must be returned
- # Variables from calling programs must be restored

# Register Windows

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- ⌘ Only few parameters
- ⌘ Limited range of depth of call
- ⌘ Use multiple small sets of registers
- ⌘ Calls switch to a different set of registers
- ⌘ Returns switch back to a previously used set of registers

# Register Windows cont.

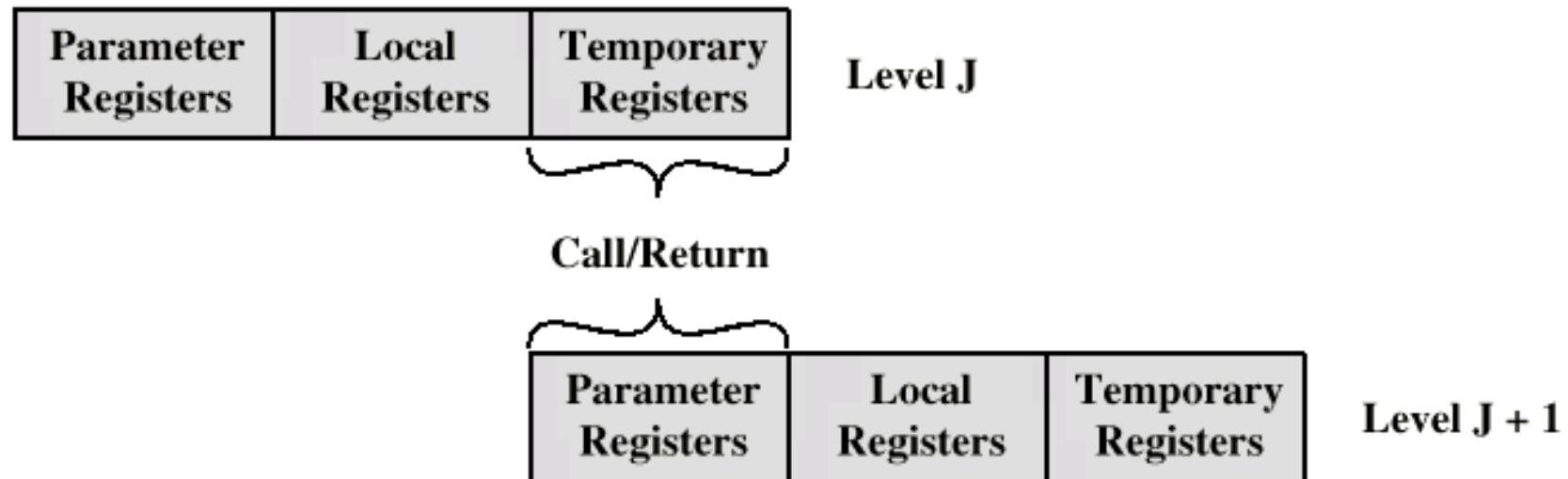
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## ⌘ Three areas within a register set

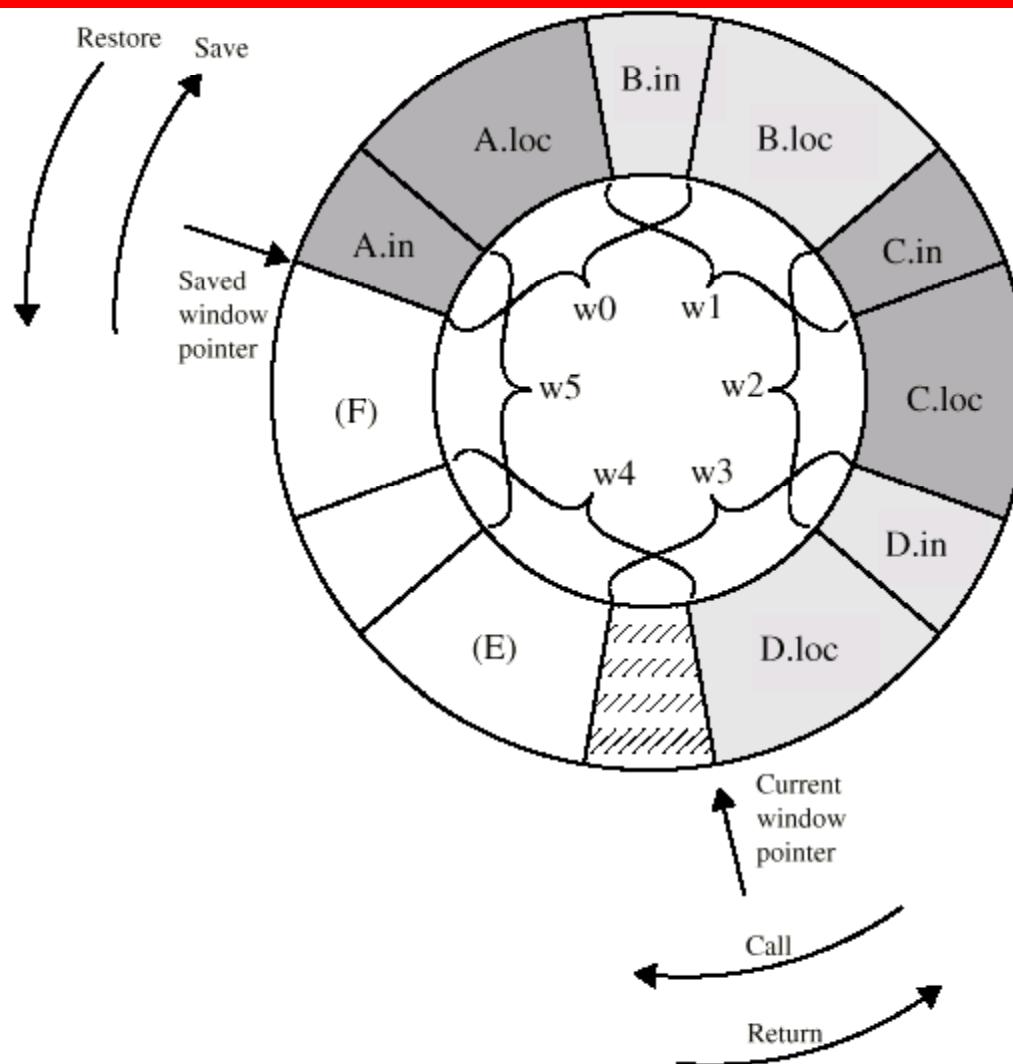
- ↗ Parameter registers
- ↗ Local registers
- ↗ Temporary registers
- ↗ Temporary registers from one set overlap parameter registers from the next
- ↗ This allows parameter passing without moving data

# Overlapping Register Windows

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# Circular Buffer diagram



# Operation of Circular Buffer

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- ⌘ When a call is made, a current window pointer is moved to show the currently active register window
- ⌘ If all windows are in use, an interrupt is generated and the oldest window (the one furthest back in the call nesting) is saved to memory
- ⌘ A saved window pointer indicates where the next saved windows should restore to

# Global Variables

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- ⌘ Allocated by the compiler to memory
  - ✗ Inefficient for frequently accessed variables
- ⌘ Have a set of registers for global variables

# Registers v Cache

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## ⌘ Large Register File

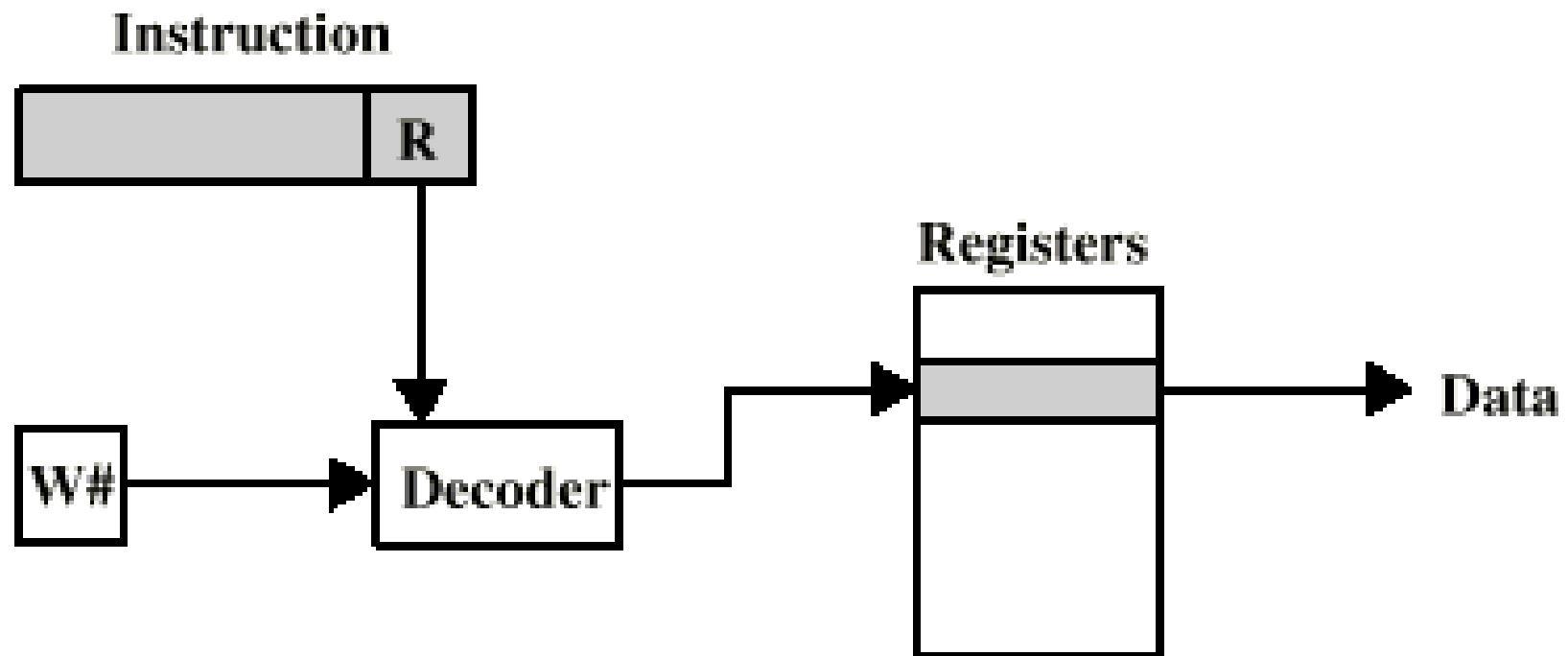
- ⌘ All local scalars
- ⌘ Individual variables
- ⌘ Compiler assigned global variables
- ⌘ Save/restore based on procedure nesting
- ⌘ Register addressing

## Cache

- Recently used local scalars
- Blocks of memory
- Recently used global variables
- Save/restore based on caching algorithm
- Memory addressing

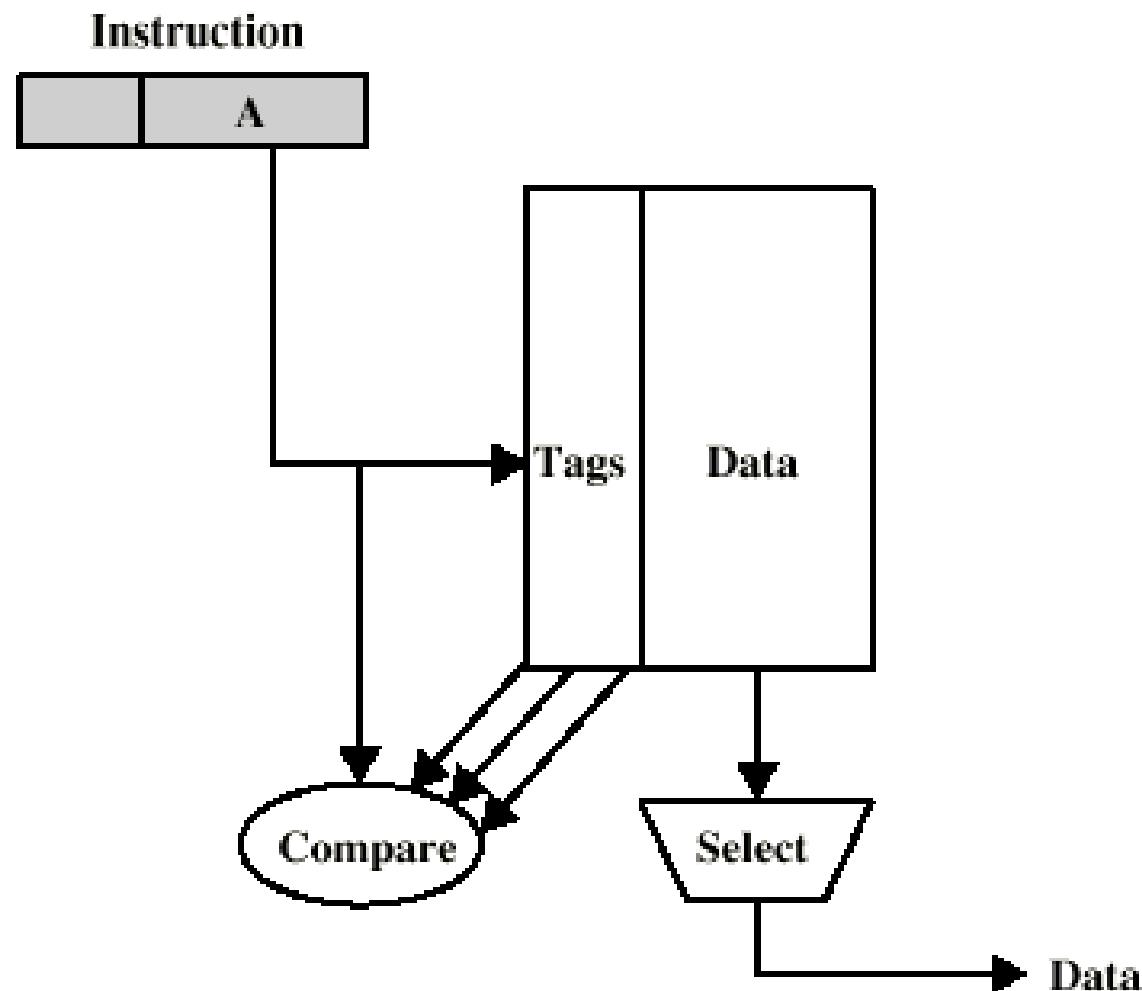
# Referencing a Scalar - Window Based Register File

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# Referencing a Scalar - Cache

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# Compiler Based Register Optimization

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- # Assume small number of registers (16-32)
- # Optimizing use is up to compiler
- # HLL programs have no explicit references to registers
  - ☒ usually - think about C - register int
- # Assign symbolic or virtual register to each candidate variable
- # Map (unlimited) symbolic registers to real registers
- # Symbolic registers that do not overlap can share real registers
- # If you run out of real registers some variables use memory

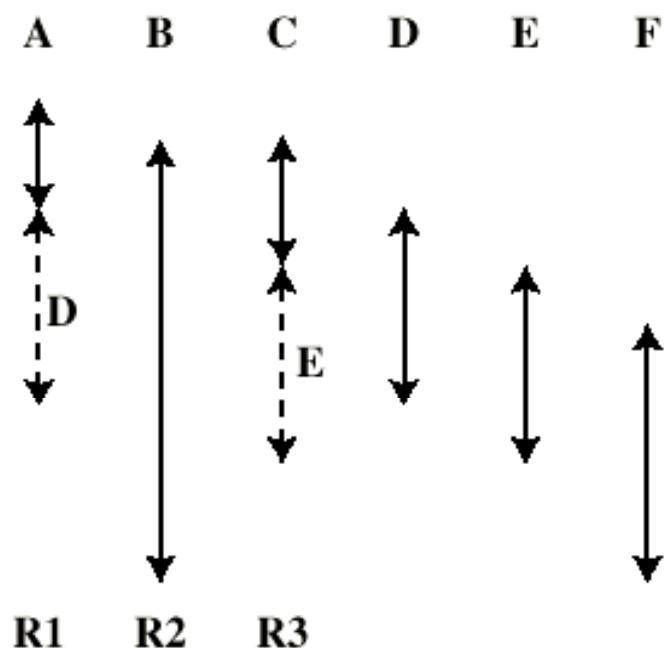
# Graph Coloring

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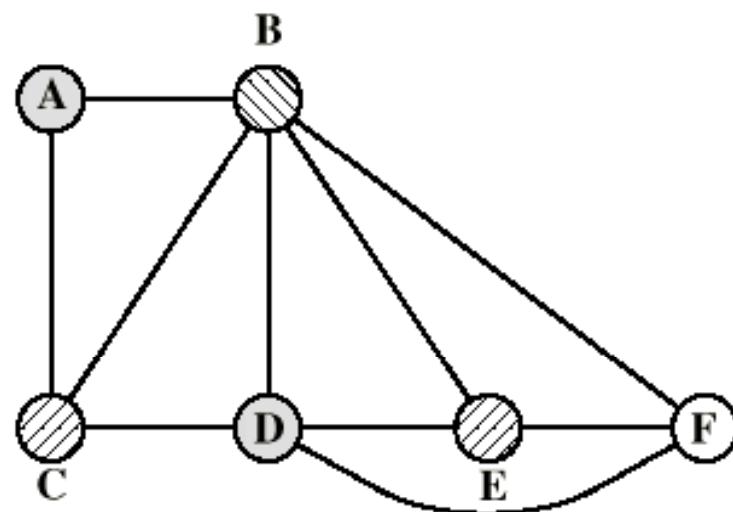
- # Given a graph of nodes and edges
- # Assign a color to each node
- # Adjacent nodes have different colors
- # Use minimum number of colors
- # Nodes are symbolic registers
- # Two registers that are live in the same program fragment are joined by an edge
- # Try to color the graph with  $n$  colors, where  $n$  is the number of real registers
- # Nodes that can not be colored are placed in memory

# Graph Coloring Approach

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(a) Time sequence of active use of registers



(b) Register interference graph

# Why CISC (1)?

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## ⌘ Compiler simplification?

- ☒ Disputed...
- ☒ Complex machine instructions harder to exploit
- ☒ Optimization more difficult

## ⌘ Smaller programs?

- ☒ Program takes up less memory but...
- ☒ Memory is now cheap
- ☒ May not occupy less bits, just look shorter in symbolic form
  - ☒ More instructions require longer op-codes
  - ☒ Register references require fewer bits

# Why CISC (2)?

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## ⌘ Faster programs?

- ☒ Bias towards use of simpler instructions
- ☒ More complex control unit
- ☒ Microprogram control store larger
- ☒ thus simple instructions take longer to execute

## ⌘ It is far from clear that CISC is the appropriate solution

# RISC Characteristics

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- # One instruction per cycle
- # Register to register operations
- # Few, simple addressing modes
- # Few, simple instruction formats
- # Hardwired design (no microcode)
- # Fixed instruction format
- # More compile time/effort

# RISC v CISC

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- ⌘ Not clear cut
- ⌘ Many designs borrow from both philosophies
- ⌘ e.g. PowerPC and Pentium II

# RISC Pipelining

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⌘ Most instructions are register to register

⌘ Two phases of execution

    ⌘ I: Instruction fetch

    ⌘ E: Execute

        ✗ ALU operation with register input and output

⌘ For load and store

    ⌘ I: Instruction fetch

    ⌘ E: Execute

        ✗ Calculate memory address

    ⌘ D: Memory

        ✗ Register to memory or memory to register operation

# Effects of Pipelining

Load A M [I | E | D]

Load B M [I | E | D]

Add C A + B [I | E]

Store M C [I | E | D]

Branch X [I | E]

(a) Sequential execution

Load A M [I | E | D]

Load B M [I | E | D]

Add C A + B [I | E]

Store M C [I | E | D]

Branch X [I | E]

NOOP [I | E]

(b) Two-way pipelined timing

Load A M [I | E | D]

Load B M [I | E | D]

NOOP [I | E]

Add C A + B [I | E]

Store M C [I | E | D]

Branch X [I | E]

NOOP [I | E]

Load A M [I | E<sub>1</sub> | E<sub>2</sub> | D]

Load B M [I | E<sub>1</sub> | E<sub>2</sub> | D]

NOOP [I | E<sub>1</sub> | E<sub>2</sub>]

Add C A + B [I | E<sub>1</sub> | E<sub>2</sub>]

Store M C [I | E<sub>1</sub> | E<sub>2</sub> | D]

Branch X [I | E<sub>1</sub> | E<sub>2</sub>]

NOOP [I | E<sub>1</sub> | E<sub>2</sub>]

NOOP [I | E<sub>1</sub> | E<sub>2</sub>]

(c) Three-way pipelined timing

(d) Four-way pipelined timing

# Optimization of Pipelining

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## ⌘ Delayed branch

- ☒ Does not take effect until after execution of following instruction
- ☒ This following instruction is the delay slot

# Normal and Delayed Branch

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Address	Normal	Delayed	Optimized
100	LOAD X,A	LOAD X,A	LOAD X,A
101	ADD 1,A	ADD 1,A	JUMP 105
102	JUMP 105	JUMP 105	ADD 1,A
103	ADD A,B	NOOP	ADD A,B
104	SUB C,B	ADD A,B	SUB C,B
105	STORE A,Z	SUB C,B	STORE A,Z
106		STORE A,Z	

# Use of Delayed Branch

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100 Load X, A      

I	E	D
---	---	---

101 Add I, A      

I	E
---	---

102 Jump 106      

I	E
---	---

103 NOOP      

I	E
---	---

106 Store A, Z      

I	E	D
---	---	---

100 Load X, A      

I	E	D
---	---	---

101 Jump 105      

I	E
---	---

102 Add I, A      

I	E
---	---

105 Store A, Z      

I	E	D
---	---	---

(a) Inserted NOOP

(b) Reversed instructions

# Controversy

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## ⌘ Quantitative

- ☒ compare program sizes and execution speeds

## ⌘ Qualitative

- ☒ examine issues of high level language support and use of VLSI real estate

## ⌘ Problems

- ☒ No pair of RISC and CISC that are directly comparable
- ☒ No definitive set of test programs
- ☒ Difficult to separate hardware effects from compiler effects
- ☒ Most comparisons done on “toy” rather than production machines
- ☒ Most commercial devices are a mixture

# Required Reading

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- ⌘ Stallings chapter 12
- ⌘ Manufacturer web sites

